## Geometry Lecture Notes

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Revised: Fall 2006

This is not a complete set of lecture notes for Math 345, Geometry. Additional material will be covered in class and discussed in the textbook.

## Logic

In this section we give an informal overview of logic and proofs. For a more formal introduction see any logic textbook.

## Variables, Expressions, and Statements

Definition $A$ set is a collection of items called the members (or elements) of the set.
Remark An element is either in a set or it is not in a set, it cannot be in a set more than once.

Definition An expression is an arrangement of symbols which represents an element of a set called the domain (or type) of the expression.

Remark It is not necessary that we know specifically which element of the domain an expression represents, only that it represents some unspecified element in that set.

Definition The element of the domain that the expression represents is called a value of that expression.
Definition A variable is an expression consisting of a single symbol.
Definition $A$ constant is an expression whose domain contains a single element.
Definition $A$ statement (or Boolean expression) is an expression whose domain is \{true, false $\}$.

Remark We do not have to know if a statement is true or false, just that it is either true or false.

Definition The value of a statement is called its truth value.
Definition To solve a statement is to determine the set of all elements for which the statement is true.

Remark More precisely, if a statement contains $n$ variables, $x_{1}, \ldots x_{n}$, then to solve the statement is to find the set of all n-tuples $\left(a_{1}, \ldots, a_{n}\right)$ such that each $a_{i}$ is an element of the domain of $x_{i}$ and the statement becomes true when $x_{1}, \ldots, x_{n}$ are replaced by $a_{1}, \ldots, a_{n}$ respectively. Each such n-tuple is called a solution of the statement.

## Definition The set of all solutions of a statement is called the solution set.

Definition An equation is a statement of the form $A=B$ where $A$ and $B$ are expressions.
Definition An inequality is a statement of the form $A \star B$ where $A$ and $B$ are expressions and $\star$ is one of $\leq, \geq,>,<$, or $\neq$.

## Propositional Logic

## The Five Logical Operators

Definition Let $P, Q$ be statements. Then the expressions

$$
\begin{aligned}
& \text { 1. } \sim P \\
& \text { 2. } P \text { and } Q \\
& \text { 3. } P \text { or } Q \\
& \text { 4. } P \Rightarrow Q \\
& \text { 5. } P \Leftrightarrow Q
\end{aligned}
$$

are also statements whose truth values are completely determined by the truth values of $P$ and $Q$ as shown in the following table

| $P$ | $Q$ | $\sim P$ | $P$ and $Q$ | $P$ or $Q$ | $P \Rightarrow Q$ | $P \Leftrightarrow Q$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $T$ | $T$ | $F$ | $T$ | $T$ | $T$ | $T$ |
| $T$ | $F$ | $F$ | $F$ | $T$ | $F$ | $F$ |
| $F$ | $T$ | $T$ | $F$ | $T$ | $T$ | $F$ |
| $F$ | $F$ | $T$ | $F$ | $F$ | $T$ | $T$ |

## Rules of Inference and Proof

Definition A rule of inference is a rule which takes zero or more statements (or other items) as input and returns one or more statements as output.
Notation An expression of the form

represents a rule of inference whose inputs are $P_{1} \ldots P_{k}$ and outputs are $Q_{1}, \ldots, Q_{n}$.
Notation The rule of inference shown above can also be expressed in recipe notation as

| $\qquad$Show $P_{1}$ <br> $\vdots$ <br> Show $P_{k}$ <br> Conclude $Q_{1}$ <br> $\vdots$ <br> or equivalently, <br> Conclude $Q_{n}$ <br> To show $Q_{1}, \ldots, Q_{n}$ <br> Show $P_{1}$ <br> $\vdots$ <br> Show $P_{k}$ |
| :--- |
| Definition A formal logic system consists of a set of statements and a set of rules of |
| inference. |
| Definition $A$ proof in a formal logic system consists of a finite sequence of statements (and |
| other inputs to the rules of inference) such that each statement follows from the previous |
| statements in the sequence by one or more of the rules of inference. |
| Natural Deduction |
| Definition The symbol $\leftarrow$ is an abbreviation for "end assumption". |
| Definition The rules of inference for propositional logic are shown in Table 1. |


| Table 1: Rules of inference for Propositional Logic |  |
| :---: | :---: |
| and + <br> To show $W$ and $V$ <br> 1. Show $W$ <br> 2. Show $V$ | and - and - <br> To show $W$ To show $V$ <br> 1. Show $W$ and $V$ 1. Show $W$ and $V$ |
| $\square$ <br> To show $W \Rightarrow V$ <br> 1. Assume $W$ <br> 2. Show $V$ <br> 3. $\leftarrow$ | $\Rightarrow$ - (modus ponens) <br> To show $V$ <br> 1. Show $W$ <br> 2. Show $W \Rightarrow V$ |
| To show $W \Leftrightarrow V$ <br> 1. Show $W \Rightarrow V$ <br> 2. Show $V \Rightarrow W$ | $\Leftrightarrow-$ $\Leftrightarrow-$ <br> To show $W \Rightarrow V$ To show $V \Rightarrow W$ <br> 1. Show $W \Leftrightarrow V$ 1. Show $W \Leftrightarrow V$ |
| or + or + <br> To show $W$ or $V$ To show $W$ or $V$ <br> 1. Show $W$ 1. Show $V$ | or - (proof by cases) <br> To show $U$ <br> 1. Show $W$ or $V$ <br> 2. Show $W \Rightarrow U$ <br> 3. Show $V \Rightarrow U$ |
| $\sim+$ (proof by contradiction) <br> To show $\sim W$ <br> 1. Assume $W$ <br> 2. Show $\rightarrow \leftarrow$ <br> $3 . \leftarrow$ | $\sim$ - (proof by contradiction) <br> To show $W$ <br> 1. Assume ~ W <br> 2. Show $\rightarrow \leftarrow$ <br> $3 . \leftarrow$ |
| $\rightarrow \leftarrow+$ <br> To show $\rightarrow \leftarrow$ <br> 1. Show $W$ <br> 2. Show $\sim W$ |  |

Remark Note that the inputs "Assume -" and " $\leftarrow$ " are not themselves statements but rather inputs to rules of inference that may be inserted into a proof at any time. There is no reason however, to insert such statements unless you intend to use one of the rules of inference that
requires them as inputs.
Remark Precedence: In order to eliminate parentheses we give the operators the following precedence (from highest to lowest):

| other math operators $(+,=, \cdot, \cup,-$, etc $)$ |
| :---: |
| $\sim$ |
| and, or |
| $\Rightarrow$ |
| $\Leftrightarrow$ |

Example Use Natural Deduction to prove the following tautologies.

1. $\sim \sim P \Leftrightarrow P$
2. $\sim(P$ and $Q) \Leftrightarrow \sim P$ or $\sim Q \quad$ [Hint: Use $P$ or $\sim P$, proven in the homework]

## Equality

Definition The equality symbol, $=$, is defined by the two rules of inference given in Table 2.

| Table 2: Rules of Inference for Equality |  |
| :--- | :--- |
| Reflexive $=$ | Substitution |
| To show $x=x$ | To show $W$ with the $n^{\text {th }}$ free occurrence of $x$ replaced by $y$ <br> 1. Show $W$ <br> $2 . S h o w ~$ <br> 2. Shy |

Remark Note that in the Reflexive rule there are no inputs, so you can insert a statement of the form $x=x$ into your proof at any time. Note that there is a technical restriction on the Substitution rule that is not listed here (see the Proof Recipes sheet for details). In most situations the restriction is not a concern.

Example Use natural deduction to prove that $x=y \Leftrightarrow y=x$.

## Quantifiers

Definition The symbols $\forall$ and $\exists$ are quantifiers. The symbol $\forall$ is called "for all", "for every", or "for each". The symbol $\exists$ is called "for some" or "there exists".

Definition If $W$ is a statement and $x$ is any variable then $\forall x, W$ and $\exists x, W$ are both statements. The rules of inference for these quantifiers are given in Table 3.

Notation If $x$ is a variable, t an expression, and $W(x)$ a statement then $W(t)$ is the statement obtained by replacing every free occurance of $x$ in $W(x)$ with $(t)$,

| Table 3: Rules of Inference for Quantifiers |  |
| :--- | :--- |
| $\forall+$ | $\forall-$ |
| To show $\forall x, W(x)$ To show $W(t)$ <br> 1. Let $s$ be arbitrary 1. Show $\forall x, W(x)$ <br> 2. Show $W(s)$  <br> $\exists+$ $\exists-$ <br> To show $\exists x, W(x)$ To show $W(t)$ for some $t$ <br> 1. Show $W(t)$ 1. Show $\exists x, W(x)$ \begin{tabular}{l}
\end{tabular} |  |

Remark Note that there are restrictions on the rules of inference for quantifiers which are not listed in Table 3 (see the Proof Recipes sheet for details). In most situations they are not a concern.

Remark Precedence: Quantifiers have a lower precedence than $\Leftrightarrow$. Thus they quantify the largest statement to their right possible unless specifically limited by parentheses.
Example Prove $(\sim \exists x, P(x)) \Rightarrow \forall x, \sim P(x)$
Example Prove $(\forall x, P(x) \Rightarrow Q(x))$ and $(\forall y, P(y)) \Rightarrow(\forall z, Q(z))$
Definition Let $W(x)$ be a statement and $W(y)$ the statement obtained by replacing every free occurance of $x$ in $W(x)$ with $y$. We define

$$
(\exists!x, W(x)) \Leftrightarrow \exists x,(W(x) \text { and } \forall y, W(y) \Rightarrow y=x)
$$

The statement $\exists!x, W(x)$ is read "There exists a unique $x$ such that $W(x)$."

| Table 4: Rules of Inference for $\exists!$ |  |
| :--- | :--- |
| $\exists!+$ | $\exists!-$ |
| To show $\exists!x, W(x)$ | To show $\exists x, W(x)$ and $\forall y, W(y) \Rightarrow y=x$ |
| 1. Show $W(t)$ | 1. Show $\exists!x, W(x)$ |
| 2. Let $y$ be arbitrary |  |
| 3. Assume $W(y)$ |  |
| 4. Show $y=t$ |  |
| 5. $\leftarrow$ |  |

## Sets, Functions, Numbers

## Some Definitions from Set theory

The symbol $\in$ is formally undefined, but it means "is an element of". Many of the definitions below are informal definitions that are sufficient for our purposes.
Set notation and operations

| Finite set notation: | $x \in\left\{x_{1}, \ldots, x_{n}\right\} \Leftrightarrow x=x_{1}$ or $\cdots$ or $x=x_{n}$ |
| :--- | :--- |
| Set builder notation: | $x \in\{y: P(y)\} \Leftrightarrow P(x)$ |
| Cardinality: | $\# S=$ the number of elements in a finite set $S$ |
| Subset: | $A \subseteq B \Leftrightarrow \forall x, x \in A \Rightarrow x \in B$ |
| Set equality: | $A=B \Leftrightarrow A \subseteq B$ and $B \subseteq A$ |
| Def. of $\notin:$ | $x \notin A \Leftrightarrow \sim(x \in A)$ |
| Empty set: | $A=\emptyset \Leftrightarrow \forall x, x \notin A$ |
| Relative Complement: | $x \in B-A \Leftrightarrow x \in B$ and $x \notin A$ |
| Intersection: | $x \in A \cap B \Leftrightarrow x \in A$ and $x \in B$ |
| Union: | $x \in A \cup B \Leftrightarrow x \in A$ or $x \in B$ |
| Indexed Intersection: | $x \in \bigcap_{i \in I} A_{i} \Leftrightarrow \forall i, i \in I \Rightarrow x \in A_{i}$ |
| Indexed Union: | $x \in \bigcup_{i \in I} A_{i} \Leftrightarrow \exists i, i \in I$ and $x \in A_{i}$ |

Two convenient abbreviations: $\quad(\forall x \in A, P(x)) \Leftrightarrow \forall x, x \in A \Rightarrow P(x)$ $(\exists x \in A, P(x)) \Leftrightarrow \exists x, x \in A$ and $P(x)$

| Some Famous Sets |  |
| :---: | :---: |
| The Natural Numbers | $\mathbb{N}=\{0,1,2,3,4, \ldots\}$ |
| The Integers | $\mathbb{Z}=\{\ldots,-3,-2,-1,0,1,2,3, \ldots\}$ |
| The Rational Numbers | $\mathbb{Q}=\left\{\frac{a}{b}: a \in \mathbb{Z}, b \in \mathbb{N}, b>0\right.$, and $\left.\operatorname{gcd}(a, b)=1\right\}$ |
| The Real Numbers | $\mathbb{R}=\{x: x$ can be expressed as a decimal number $\}$ |
| The Complex Numbers | $\mathbb{C}=\{x+y i: x, y \in \mathbb{R}\}$ where $i^{2}=-1$ |
| The positive real numbers | $\mathbb{R}^{+}=\{x: x \in \mathbb{R}$ and $x>0\}$ |
| The negative real numbers | $\mathbb{R}^{-}=\{x: x \in \mathbb{R}$ and $x<0\}$ |
| The positive reals in a set $A$ | $A^{+}=A \cap \mathbb{R}^{+}$ |
| The negative reals in a set $A$ | $A^{-}=A \cap \mathbb{R}^{-}$ |
| The first $n$ positive integers | $\mathbb{I}_{n}=\{1,2, \ldots, n\}$ |
| The first $n+1$ natural numbers $\mathbb{O}_{n}=\{0,1,2, \ldots, n\}$ |  |
| Cartesian products |  |
| Ordered Pairs: $\quad(x, y)=(u, v) \Leftrightarrow x=u$ and $y=v$ |  |
| Ordered $n$-tuple: $\left(x_{1}, \ldots, x_{n}\right)=\left(y_{1}, \ldots, y_{n}\right) \Leftrightarrow x_{1}=y_{1}$ and $\cdots$ and $x_{n}=y_{n}$ |  |
| Cartesian Product: $A \times B=\{(x, y): x \in A$ and $y \in B\}$ |  |
| Cartesian Product: $A_{1} \times \cdots \times A_{n}=\left\{\left(x_{1}, \ldots, x_{n}\right): x_{1} \in A_{1}\right.$ and $\cdots$ and $\left.x_{n} \in A_{n}\right\}$ |  |
| Power of a Set $\quad A^{n}=A \times$ | $\times \cdots \times A$ where there are $n$ " $A$ 's" in the Cartesian product |

## Functions and Relations

| Def of $\neq$ | $x \neq t \Leftrightarrow \sim(x=t)$ |
| :--- | :--- |
| Def of relation: | $R$ is a relation from $A$ to $B \Leftrightarrow R \subseteq A \times B$ |
| Def of function: | $f: A \rightarrow B \Leftrightarrow f \subseteq A \times B$ and $(\forall x, \exists!y,(x, y) \in f)$ |
| Alt function notation | $X \stackrel{f}{\rightarrow} Y \Leftrightarrow f: X \rightarrow Y$ |
| Def of $f(x):$ | $f(x)=y \Leftrightarrow f: A \rightarrow B$ and $(x, y) \in f$ |
| Domain: | Domain $(f)=A \Leftrightarrow f: A \rightarrow B$ |
| Codomain: | Codomain $(f)=B \Leftrightarrow f: A \rightarrow B$ |
| Image (of a set): | $f(S)=\{y: \exists x, x \in S$ and $y=f(x)\}$ |
| Range (or Image of $f):$ | Range $(f)=f(\operatorname{Domain}(f))$ |
| Identity Map: | $i d_{A}: A \rightarrow A$ and $\forall x, i d_{A}(x)=x$ |
| Composition: | $f: A \rightarrow B$ and $g: B \rightarrow C \Rightarrow(g \circ f): A \rightarrow C$ and $\forall x,(g \circ f)(x)=g(f(x))$ |
| Injective (one-to-one): | $f$ is injective $\Leftrightarrow \forall x, \forall y, f(x)=f(y) \Rightarrow x=y$ |
| Surjective (onto): | $f$ is surjective $\Leftrightarrow f: A \rightarrow B$ and $(\forall y, y \in B \Rightarrow \exists x, y=f(x))$ |
| Bijective: | $f$ is bijective $\Leftrightarrow f$ is injective and $f$ is surjective |
| Inverse: | $f^{-1}: B \rightarrow A \Leftrightarrow f: A \rightarrow B$ and $f \circ f^{-1}=i d_{B}$ and $f^{-1} \circ f=i d_{A}$ |
| Inverse Image: | $f: A \rightarrow B$ and $S \subseteq B \Rightarrow f^{-1}(S)=\{x \in A: f(x) \in S\}$ |

Example Prove $(A-B) \subseteq(A \cup B)-(A \cap B)$
Example Prove the composition of bijective functions is bijective.

## Equivalence Relations

Definition Let $X$ be a set.

$$
R \text { is a relation on } X \Leftrightarrow R \subseteq X \times X \text {. }
$$

Definition Let $X$ be a set and $R \subseteq X \times X$. For any $x, y \in X$,

$$
x R y \Leftrightarrow(x, y) \in R \quad \text { (infix notation) }
$$

and

$$
R(x, y) \Leftrightarrow(x, y) \in R \quad \text { (prefix notation) }
$$

Definition Let $X$ be a set and $R \subseteq X \times X$.
$R$ is an equivalence relation $\Leftrightarrow \quad \forall x, y, z \in X$,
(0) $x R x$ (reflexive)
(1) $x R y \Rightarrow y R x \quad$ (symmetric)
(2) $x R y$ and $y R z \Rightarrow x R z$ (transitive)

Definition Let $R \subseteq X \times X$ be an equivalence relation and $a \in X$.

$$
[a]_{R}=\{x: x R a\}
$$

This is called the equivalence class of a (with respect to $R$ ).
Notation We often abbreviate $[a]_{R}$ by $[a]$ when the relation $R$ is clear from context.
Theorem (Fundamental Theorem of Equivalence Relations) Let $R \subseteq X \times X$ be an equivalence relation and $a, b \in X$. Then

$$
[a]=[b] \Leftrightarrow a R b .
$$

Corollary (1) Let $R \subseteq X \times X$ be an equivalence relation. Then $X$ is a disjoint union of equivalence classes, i.e.

$$
X=\bigcup_{a \in X}[a]
$$

and

$$
\forall a, b \in X,[a]=[b] \text { or }[a] \cap[b]=\emptyset .
$$

Definition If $X$ is a set and $P=\left\{A_{i}: i \in I\right\}$ is a set of subsets of $X$ such that

$$
X=\bigcup_{i \in I} A_{i}
$$

and

$$
\forall i, j \in I, i \neq j \Rightarrow A_{i} \cap A_{j}=\emptyset
$$

we say that $P$ is a partition of $X$.
Remark Thus, the set of equivalence classes of an equivalence relation on $X$ is a partition of X.

## Counting

Definition Two sets have the same cardinality if and only if there is a bijection from one set to the other.

Definition $A$ finite set $A$ has $n$ elements if and only if there is a bijection from $\{1,2,3, \ldots, n\}$ to $A$.

Remark If two sets have the same cardinality then they are both infinite, or both finite. If they are finite the have the same number of elements.

## Toy Geometries

## Incidence Structure

Definition An incidence structure is an ordered pair of sets $(\mathcal{P}, \mathcal{L})$ such that $\mathcal{L}$ is a set of subsets of $\mathcal{P}$. The elements of the set $\mathcal{P}$ are called points and the elements of the set $\mathcal{L}$ are called lines. If $A$ is a point and $l$ is a line then the following phrases all mean the same thing: "A $\in l$ ", " $A$ is on $l$ ", " $A$ is contained in $l$ ", " $A$ is incident with $l$ ", "l goes through $A$ ", " $l$ contains $A$ ".

Example ( $\{\quad\},\{\quad\})$ is a trivial incidence structure.

Example ( $\{\wedge, \star, \triangleright\},\{\{\wedge\},\{\wedge, \triangleright\},\{\star, \triangleright\}\})$ is an incidence structure. In this structure $\uparrow, \bigcirc$ are collinear points (see below), but $\uparrow$, \& are not.

Example ( $\left.\mathbb{R}^{2}, \mathcal{L}\right)$ where
$\mathcal{L}=\left\{l: l=\left\{(x, y) \in \mathbb{R}^{2}: a x+b y+c=0\right\}\right.$ for some $a, b, c \in \mathbb{R}$ with $a \neq 0$ or $\left.b \neq 0\right\}$ is an incidence structure.

Definition $A$ figure in an incidence structure is a subset of the set of points.
Definition Two lines in an incidence structure intersect if and only if they have a point in common, i.e. l intersects $m$ iff there exists $A$ such that $A$ is on land $A$ is on $m$. In this situation we say that the lines $l$ and $m$ intersect at $A$. A set of lines, all of which contain a point $A$ are said to be concurrent.

Definition The points in a figure are collinear if there exists a line containing every point in the figure.

Definition Two lines $l, m$ are parallel if and only if $l \cap m=\emptyset$. We write $l \| m$ as an abbreviation for " $l$ is parallel to $m$ ".

Example Which pairs of lines are parallel in the previous examples?
Definition Let l be a line in an incidence structure. Then the parallel class ofl is the set consisting of l and all lines parallel to $l$. We denote this set as ParallelClass(l).

Example What is the parallel class of $\{\wedge, \odot\}$ in the second example above?
Example What is the parallel class of the line $\{(x, y): x+y+1=0\}$ in the third example above?

Definition Let $A$ be a point in an incidence structure. Then the pencil of lines through $A$ is the set consisting of all lines containing the point $A$. We denote this set as Pencil( $A$ ).

Example What is the pencil of lines through $\uparrow$ in the second example above?
Example What is the pencil of lines through the origin in the third example above?
Notation To simplify notation capital letters will represent points and lower case letters will represent lines unless specifically stated otherwise. This applies to variables bound by quantifiers also.

Remark From now on, whenever we discuss points and lines, we will be referring to elements of some incidence structure unless specifically stated otherwise.

Example Prove or disprove that in any incidence structure no two distinct points can have the same pencil of lines.

Example Let $l, m, n$ be distinct lines in an incidence structure ( $\mathcal{P}, \mathcal{L}$ ). Prove or disprove that if $l \| m$ and $n$ intersects both $l$ and $m$, then there exist at least two points.

Example Let $\left(\mathbb{R}^{2}, \mathcal{L}\right)$ be the incidence structure defined by

$$
\mathcal{L}=\left\{l: l=\left\{(x, y) \in \mathbb{R}^{2}: y=m x+b\right\} \text { for some } m, b \in \mathbb{R}\right\}
$$

Prove or disprove that two nonvertical lines are parallel if and only if they have the same slope and different y-intercepts.

## Affine Planes

Definition An affine plane is an incidence structure satisfying the following three axioms.
A1. There is a unique line through any two distinct points.
A2. Through any point not on a given line, there is a unique line parallel to the given line
A3. There are three points which are not collinear.
Remark More formally an affine plane is an incidence structure ( $\mathcal{P}, \mathcal{L}$ ) satisfying the following three axioms:

A1. $\forall A, B, A \neq B \Rightarrow \exists!l, A \in l$ and $B \in l$
A2. $\forall A \forall l, A \notin l \Rightarrow \exists!m, A \in m$ and $m \| l$
$A 3 . \exists A, B, C, A \neq B$ and $B \neq C$ and $A \neq C$ and $\forall l, \sim(A \in l$ and $B \in l$ and $C \in l)$
Definition Let $A, B$ be distinct points in any incidence structure satisfying axiom A1. Then the unique line through $A$ and $B$ is denoted $\overleftrightarrow{A B}$.

Example The Cartesian plane $\left(\mathbb{R}^{2}, \mathcal{L}\right)$ example given above is an affine plane.
Example Let $\mathcal{P}=\{A, B, C, D\}$ and $\mathcal{L}=\{\{A, B\},\{A, C\},\{A, D\},\{B, C\},\{B, D\},\{C, D\}\}$. Then $(\mathcal{P}, \mathcal{L})$ is an affine plane.

## Theorem Two distinct lines in an affine plane can intersect in at most one point.

## Proof:

1. Let $l$ and $m$ be lines in an affine plane with $l \neq m$
2. Assume $l, m$ intersect at more than one point
3. $l, m$ intersect at points $A, B$ for some $A, B$ with $A \neq B$
4. $\quad A$ is on $l$ and $A$ is on $m$ and $B$ is on $l$ and $B$ is on $m$
def of "more than one";2
5. $\quad l=\overleftrightarrow{A B}$ and $m=\overleftrightarrow{A B}$
def of "intersect at";3
6. $l=m$
7. $\rightarrow \leftarrow$

A1 (or def of $\overleftrightarrow{A B}$ ); 4
8. $\leftarrow$
9. $l, m$ do not intersect at more than one point
subst;5,5
$\rightarrow \leftarrow+; 1,6$
$\sim+; 2,7,8$
QED
Definition An affine plane $(\mathcal{P}, \mathcal{L})$ where $\mathcal{P}$ is a finite set of points is called a finite affine plane.

Theorem In any finite affine plane, if one line consists of exactly n points, then every line consists of exactly $n$ points.
Proof: Homework.
Definition An affine plane in which every line has $n$ points is called an affine plane of order $n$.

## Projective Planes

## Definition A projective plane is an incidence structure satisfying the following three

 axioms.P1. There is a unique line through any two distinct points.
P2. There is a unique point on any two distinct lines.
P3. There are four distinct points, no three of which are collinear.
Remark More formally a projective plane is an incidence structure ( $\mathcal{P}, \mathcal{L}$ ) satisfying the following three axioms:

P1. $\forall A, B, A \neq B \Rightarrow \exists!l, A \in l$ and $B \in l$
P2. $\forall l, m, l \neq m \Rightarrow \exists!A, A \in l$ and $A \in m$
P3. $\exists A, B, C, D, A \neq B$ and $A \neq C$ and $A \neq D$ and $B \neq C$ and $B \neq D$ and $C \neq D$ and $\sim \exists l,(A \in l$ and $B \in l$ and $C \in l)$ or $(A \in l$ and $B \in l$ and $D \in l)$ or $(A \in l$ and $C \in l$ and $D \in l)$ or $(B \in l$ and $C \in l$ and $D \in l)$

Remark Since a projective plane satisfies P1 the unique line through $A$ and $B$ is still denoted $\overleftrightarrow{A B}$

Remark The formal version of P3 shows why we don't use strictly formal proofs for everything! Yuk!
Example Let $\mathcal{P}=\{A, B, C, D, E, F, G\}$ and

$$
\mathcal{L}=\{\{A, B, C\},\{C, D, E\},\{A, E, F\},\{A, D, G\},\{B, E, G\},\{C, F, G\},\{B, D, F\}\}
$$

Then $(\mathcal{P}, \mathcal{L})$ is a projective plane.
Example Let $\mathcal{P}$ be the set of (Euclidean) lines through the origin in $\mathbb{R}^{3}$ and $\mathcal{L}$ be the set of planes through the origin in $\mathbb{R}^{3}$. Then $(\mathcal{P}, \mathcal{L})$ is a projective plane.
Proof: [Note: In the following proof we assume all elementary facts about the Euclidean geometry of $\mathbb{R}^{3}$ are given.]

1. Let $\mathcal{P}$ be the set of (Euclidean) lines through the origin in $\mathbb{R}^{3}$
and $\mathcal{L}$ be the set of planes through the origin in $\mathbb{R}^{3}$
2. Let $A, B$ be distinct points in $(\mathcal{P}, \mathcal{L})$
3. $A, B$ are Euclidean lines through the origin in $\mathbb{R}^{3}$
4. There exists a unique plane in $\mathbb{R}^{3}$ containing $A$ and $B$
5. There exists a unique line in $(\mathcal{P}, \mathcal{L})$ containing $A$ and $B$
6. $(\mathcal{P}, \mathcal{L})$ satisfies axiom $P 1$
7. Let $l, m$ be distinct lines in $(\mathcal{P}, \mathcal{L})$
8. $l, m$ are planes in $\mathbb{R}^{3}$ passing through the origin
9. The intersection of $l, m$ is a Euclidean line
10. The origin is on $l$ and the origin is on $m$
11. The origin is on the intersection of $l, m$
12. The intersection of $l, m$ is a unique Euclidean line through the origin
13. $l, m$ intersect at a unique point in $(\mathcal{P}, \mathcal{L})$
14. $(\mathcal{P}, \mathcal{L})$ satisfies axiom $P 2$
15. Let $A, B, C, D$ be the $x$-axis, $y$-axis, $z$-axis, and the line through $(1,1,1)$ and the origin in $\mathbb{R}^{3}$ respectively
16. $A, B, C, D$ are distinct lines through the origin in $\mathbb{R}^{3}$
17. $A, B, C, D$ are distinct points in $(\mathcal{P}, \mathcal{L})$
18. The planes in $\mathbb{R}^{3}$ determined by any two of $A, B, C, D$ are distinct
19. The lines in $(\mathcal{P}, \mathcal{L})$ determined by any two of $A, B, C, D$ are distinct
20. No three of the points $A, B, C, D$ are collinear in $(\mathcal{P}, \mathcal{L})$
21. There exist four distinct points in $(\mathcal{P}, \mathcal{L})$, no three of which are collinear
22. $(\mathcal{P}, \mathcal{L})$ satisfies axiom $P 3$
23. ( $\mathcal{P}, \mathcal{L})$ is a projective plane

QED
Example Let $(\mathcal{P}, \mathcal{L})$ be an affine plane. Construct a new incidence structure $\left(\mathcal{P}^{\prime}, \mathcal{L}^{\prime}\right)$ as follows. For each parallel class $\mathcal{C}$ in $(\mathcal{P}, \mathcal{L})$ let $P_{\mathcal{C}}$ be a new point distinct from those already in $\mathcal{P}$ and each other. Define $\mathcal{P}^{\prime}=\mathcal{P} \cup\left\{P_{\mathcal{C}}: \mathcal{C}\right.$ a parallel class of $\left.\mathcal{L}\right\}$ and

$$
\mathcal{L}^{\prime}=\left\{l \cup\left\{P_{\mathcal{C}}\right\}: l \in \mathcal{C}\right\} \cup\left\{\mathcal{P}^{\prime}-\mathcal{P}\right\}
$$

i.e. $\mathcal{P}^{\prime}$ consists of all of the points in $\mathcal{P}$ plus one new point for each parallel class, and $\mathcal{L}^{\prime}$ is obtained from $\mathcal{L}$ by adding to each line the new point in its parallel class and one additional line consisting of all of the new points. Then $\left(\mathcal{P}^{\prime}, \mathcal{L}^{\prime}\right)$ is a projective plane. (proof: homework). The projective plane $\left(\mathcal{P}^{\prime}, \mathcal{L}^{\prime}\right)$ is called the projective completion of the affine plane ( $\mathcal{P}, \mathcal{L}$ ).

Example Similarly if we start with a projective plane and remove a single line and all of the points on that line, while maintaining the collinearity of the points that remain, we obtain an affine plane.

Definition A projective plane $(\mathcal{P}, \mathcal{L})$ where $\mathcal{P}$ is a finite set of points is called a finite projective plane.

Theorem In any finite projective plane, if one line consists of exactly n points, then every line consists of exactly $n$ points.
Proof: Homework.
Definition A projective plane in which every line has $n+1$ elements is called a projective plane of order $n$. (It is the projective completion of an affine plane of order $n$.)

## Axioms for Euclidean Geometry

There are many different axiom systems for Euclidean geometry, and in particular Euclidean plane geometry. Here are a few notable ones.

- Euclid's Axioms - (300 BC) Euclid's Elements is perhaps one of the most famous works of all time. This 13 book treatise basically defined geometry for 2000 years until modern mathematicians created alternative geometries over the past two centuries. ( 5 axioms and

5 common notions)

- Hilbert's Axioms - (1899) this set of Axioms was created by David Hilbert to bring Euclid's work up to modern standards of rigor. ( 20 axioms and 6 undefined terms)
- Tarski's Axioms - (1929) developed an "minimalist" axiom system with only two undefined terms ("between" and "congruent") and eleven axioms
- Birchoff's Axioms - (1932) developed an axiom system using the real numbers (4 axioms and 4 undefined terms, not counting those needed to define the real numbers)
- Bachmann's Axioms - (1959) an axiom system for several geometries defined entirely in terms of abstract algebra, where points and lines are defined to be elements of a group. (8 axioms and two undefined terms, but more are needed to restrict to Euclidean geometry)
- SMSG Axioms - (~1960) the School Mathematics Study Group axioms were developed to come up with an intuitive, easy to use, but not necessarily independent set of axioms that could be used for a rigorous development of geometry that is appropriate for high school students. Like Birchoff it also uses the real numbers. (3 undefined terms, 22 axioms, not counting those needed to define the real numbers, but covers three dimensional Euclidean geometry as well as the Euclidean geometry of the plane)


## The Role of Diagrams

Diagrams are very useful in Euclidean geometry to illustrate the concepts and build intuition. However much care must be taken to not rely too heavily on what seems apparent from a diagram, as it can lead to disaster as illustrated in the following "theorem".
"Theorem": All triangles are isosceles.

"Proof": Let $\triangle A B C$ be an arbitrary triangle and let $O$ be the intersection of the angle bisector of $\angle A$ with the perpendicular bisector of $B C$ as shown in the diagram. Constuct the feet of the perpediculars from $O$ to the other sides and verify that $\triangle O B D \equiv \triangle O C D, \triangle O A E \equiv \triangle O A F$, and $\triangle O B E \equiv \triangle O C F$. Hence the triangle is isosceles.
~QED

## SMSG Axioms for Euclidean Plane Geometry

Out of nothing I have created a strange new universe. -János Bolyai

The following axioms, definitions, and theorems are based on those developed by the original School Mathematics Study Group. I have modified them slightly to be consistent with other things we are doing in the course.

Definition The Euclidean plane, $\mathbb{E}$, is an incidence structure ( $\mathcal{P}, \mathcal{L}$ ) satisfying the following axioms and definitions. The axioms are labeled $\boldsymbol{S} 1, \boldsymbol{S} \mathbf{2}, \boldsymbol{S} \mathbf{3}$, etc.

Remark Unless otherwise stated, upper case letters like $A, B, C$ represent points and lower case letters such as l,m,n represent lines.
(two points determine a line)
S1: For any two distinct points there is exactly one line which contains them both.
(distance axiom)
S2: To any two distinct points there corresponds a unique positive number.
Definition The unique positive number corresponding to a pair of distinct points is called the distance between the points. The distance between a point and itself is defined to be 0 . The distance between any two points $A$ and $B$ is denoted $d(A, B)$ or $|A B|$.

Remark Note that the order of the points doesn't matter so that $d(A, B)=d(B, A)$ for all points $A, B$.
(coordinate axiom)
S3: The points on a line can be placed into a bijective correspondence with the real numbers such that the distance between two points is the absolute value of the difference between their corresponding numbers.
Definition For each line land correspondence with the real numbers given by $\boldsymbol{S 3}$, define $\Psi(A)$ to be the real number corresponding to the point $A$ on $l$. By axiom $S 3, \Psi: l \rightarrow \mathbb{R}$ is a bijection satisfying $d(A, B)=|\Psi(B)-\Psi(A)|$ for all points $A$ and $B$ on $l$. The function $\Psi$ is called a coordinate system for the line $l$ and $\Psi(A)$ is called the coordinate of point $A$.
(ruler placement axiom)
S4: For any line $l$ and any points $A$ and $B$ on $l$, there exists a coordinate system $\Psi$ for $l$ such that $\Psi(A)=0$ and $\Psi(B)>0$.
(noncollinear points exist)
S5: There exist three noncollinear points.

Definition Point $B$ is between points $A$ and $C$ if and only if
(i) $A, B, C$ are distinct collinear points and
(ii) $|A C|=|A B|+|B C|$

If $B$ is between $A$ and $C$ we write $A . B$. C..
Definition For any two distinct points $A, B$ the segment $A B$ is the set consisting of the points $A, B$ and all points $C$ with $A$.C.B, i.e.

$$
A B=\{C: A . C . B \text { or } C=A \text { or } C=B\}
$$

The points $A$ and $B$ are called the endpoints of segment $A B$.
Definition The distance $|A B|$ is called the length of the segment $A B$.
Definition For any two distinct points $A, B$ then $\boldsymbol{r a y} \overrightarrow{A B}$ is the set consisting of the points $A, B$ and all points $C$ with $A$. C.B or $A . B . C$, i.e.

$$
\overrightarrow{A B}=\{C: A . C . B \text { or } A . B . C \text { or } C=A \text { or } C=B\}
$$

The point $A$ is called the endpoint or vertex of ray $\overrightarrow{A B}$.
Definition If $B . A$. C then $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are called opposite rays.
Definition $A$ point $M$ is called a midpoint of segment $A B$ if and only if $A . M . B$ and $|A M|=|M B|$.

Definition Any figure whose intersection with a line segment is a midpoint of the segment is said to bisect the segment.

Definition $A$ figure $F$ is convex if and only if for any two distinct points $A, B \in F, A B \subseteq F$.
(separation axiom)
S6: Every line $l$ divides the set of points not on $l$ into two disjoint convex sets $L$ and $R$ such that for any $P \in L$ and $Q \in R$ the segment $P Q$ contains a point on $l$.

Definition The sets $L$ and $R$ in axiom S6 are called half-planes and the line $l$ is called an edge of each of them. We say that l separates the Euclidean plane into two half-planes. If two points $A$ and $B$ are contained in the same half-plane we say that they are on the same side of l. If $A$ is in one half-plane and $B$ in the other we say that they are on opposite sides of $l$.

Definition An angle is the union of two rays having a common end point which are not contained in a single line. The rays are called the sides of the angle and the common endpoint is called the vertex of the angle. If the two sides of an angle are $\overrightarrow{A B}$ and $\overrightarrow{A C}$ we denote this angle as $\angle B A C$.
(angle measure)
S7: To each angle there corresponds a unique real number strictly between 0 and 180 .

> Definition The number corresponding to a given angle described in axiom $S 7$ is called the measure of the angle. The measure of $\angle B A C$ is denoted $|\angle B A C|$ or $m \angle B A C$. (It is also often denoted $\angle B A C$ when the distinction between the angle and its measure is clear from context.)

> Definition If $A, B, C$ are non-collinear points then the union of the segments $A B, B C, C A$ is called a triangle and denoted $\triangle A B C$, i.e. $\triangle A B C=A B \cup B C \cup C A$. The segments $A B, B C, C A$ are called the sides of the triangle. The angles of the triangle $\triangle A B C$ are $\angle B A C, \angle A B C$, and $\angle A C B$. When it is clear from context these angles are often abbreviated by $\angle A, \angle B$, and $\angle C$ respectively, and the lengths of sides $A B, B C$, and $C A$ are often denoted as $c, a$, and $b$ respectively. The side $A B$ is called the side opposite angle $\angle C$ in the triangle and similarly
for the other two pairs of sides and angles.
Definition The interior of $\angle B A C$ is the set of points $P$ such that $B$ and $P$ are on the same side of $\overleftrightarrow{A C}$ and $C$ and $P$ are on the same side of $\overleftrightarrow{A B}$. The exterior of an angle is the set of all points not in the interior or on the angle itself.
(angle construction)
S8: Let $\overrightarrow{A B}$ be a ray on the edge of the half plane $H$. For every real number $r$ between 0 and 180 there exists exactly one ray $\overrightarrow{A P}$ with $P$ in $H$ such that $|\angle B A P|=r$.

Remark Note that by axiom S8 every half-plane is nonempty, because it contains the point P.
(angle addition)
S9: If $D$ is a point on the interior of $\angle B A C$ then $|\angle B A C|=|\angle B A D|+|\angle C A D|$.
Definition If $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are opposite rays and $\overrightarrow{A D}$ is another ray then $\angle B A D$ and $\angle C A D$ are called a linear pair of angles. If $\overrightarrow{A C}$ and $\overrightarrow{A B}$ are opposite rays, we will sometimes find it convenient to say $\angle C A B$ is a straight angle even though it technically is not an angle.
Definition Two angles are supplementary if the sum of their measures is 180. If two angles are supplementary each angle is called a supplement of the other.

Definition Two angles are complementary if the sum of their measures is 90 . If two angles are supplementary each angle is called a complement of the other.
(supplement axiom)
S10: If two angles form a linear pair, then they are supplementary.
Definition If two angles in a linear pair have the same measure then each is called a right angle.
Definition Two intersecting figures, each of which is either a line, ray, or segment, are perpendicular if the lines containing them determine a right angle.

Definition The perpendicular bisector of a segment is the line containing the midpoint that is perpendicular to the segment.

Definition Angles are congruent angles if and only if they have the same measure. Segments are congruent segments if and only if they have the same length. If $A B$ is congruent to $C D$ we write $A B \equiv C D$ and similarly if $\angle A B C$ is congruent to $\angle D E F$ we write $\angle A B C \equiv \angle D E F$.

Definition In triangles $\triangle A B C$ and $\triangle A^{\prime} B^{\prime} C^{\prime}$ if $A B \equiv A^{\prime} B^{\prime}, B C \equiv B^{\prime} C^{\prime}, C A \equiv C^{\prime} A^{\prime}$, $\angle A \equiv \angle A^{\prime}, \angle B \equiv \angle B^{\prime}$, and $\angle C \equiv \angle C^{\prime}$ then we say that triangle $\triangle A B C$ and $\triangle A^{\prime} B^{\prime} C^{\prime}$ are congruent triangles and write $\triangle A B C \equiv \triangle A^{\prime} B^{\prime} C^{\prime}$. The three pairs of segments and three pairs of angles are called corresponding parts of the two (not necessarily distinct) triangles. Conversely, if $\triangle A B C \equiv \triangle A^{\prime} B^{\prime} C^{\prime}$ then there exists a bijective correspondence

$$
\begin{aligned}
& \xi:\{A, B, C\} \rightarrow\left\{A^{\prime}, B^{\prime}, C^{\prime}\right\} \text { such that if } D=\xi(A), E=\xi(B) \text {, and } F=\xi(C) \text { and } A B \equiv D E \text {, } \\
& B C \equiv E F, C A \equiv F D, \angle A \equiv \angle D, \angle B \equiv \angle E, \text { and } \angle C \equiv \angle F \text {. In this situation we say } A B \\
& \text { and } D E, B C \text { and } E F, A C \text { and } D F, \angle A \text { and } \angle D, \angle B \text { and } \angle E \text {, and } \angle C \text { and } \angle F \text {, are } \\
& \text { corresponding parts, and each pair of corresponding parts are congruent. }
\end{aligned}
$$

Remark Note: that for convenience, whenever possible, we indicate the function $\xi$ by listing the points in the name of the triangles involved in a congruence relation in the order that they correspond to each other, e.g. if $\triangle A B C \equiv \triangle A^{\prime} B^{\prime} C^{\prime}$ we can and should assume that $\xi(A)=A^{\prime}, \xi(B)=B^{\prime}$, and $\xi(C)=C^{\prime}$ whenever it is convenient and causes no logical problems.
(SAS)
S11: If $A B \equiv A^{\prime} B^{\prime}, B C \equiv B^{\prime} C^{\prime}$, and $\angle B \equiv \angle B^{\prime}$ then $\triangle A B C \equiv \triangle A^{\prime} B^{\prime} C^{\prime}$.
(parallel axiom)
S12: Through any point not on a given line there is exactly one line that is parallel to the given line.

## Definition $A$ polygon is any figure consisting entirely of segments $A_{1} A_{2}$,

$A_{2} A_{3}, \ldots A_{n-1} A_{n}, A_{n} A_{1}$ having the property that no two of these segments intersect except at their endpoints as specified, and no two segments that intersect are collinear. The segments $A_{i} A_{j}$ are called the sides of the polygon and the points $A_{1}, A_{2}, \ldots A_{n}$ are called its vertices.

Definition A triangular region is the union of a triangle and its interior. A polygonal region is a union of finitely many triangular regions such that if any two of them intersect, they intersect only in a segment or a point.
(area axiom)
S13: To every polygonal region corresponds a unique positive real number.
Definition The positive real number associated with a polygonal region given by axiom S13 is called the area of the polygonal region (or simply the area of the polygon).
(congruence preserves area)
S14: If two triangles are congruent then they have the same area.
(area addition)
S15: If two regions intersect in at most a finite number of segments and points, then the area of their union is the sum of their areas.
(area of a rectangle axiom)
S16: The area of a rectangle is the product of the length of two of its sides that share a vertex.

## Euclidean Plane Geometry Axioms - Quick Reference

S1: (two points determine a line) For any two distinct points there is exactly one line which contains them both.

S2: (distance axiom) For each pair of distinct points there corresponds a unique positive number.

S3: (coordinate axiom) The points on a line can be placed into a bijective correspondence with the real numbers such that the distance between two points is the absolute value of the difference between their corresponding numbers

S4: (ruler placement axiom) For any line $l$ and any points $A$ and $B$ on $l$, there exists a coordinate system $\Psi_{l}$ such that $\Psi_{l}(A)=0$ and $\Psi_{l}(B)>0$.

S5: (noncollinear points exist) There exist three noncollinear points.
S6: (separation axiom) Every line $l$ divides the set of points not on $l$ into two disjoint convex sets $L$ and $R$ such that for any $P \in L$ and $Q \in R$ the segment $P Q$ contains a point on $l$.

S7: (angle measure) To each angle there corresponds a unique real number between 0 and 180 inclusive.

S8: (angle construction) Let $\overrightarrow{A B}$ be a ray on the edge of the half plane $H$. For every real number $r$ between 0 and 180 there exists exactly one ray $\overrightarrow{A P}$ with $P$ in $H$ such that $|\angle B A P|=r$.

S9: (angle addition) If $D$ is a point on the interior of $\angle B A C$ then $|\angle B A C|=|\angle B A D|+|\angle C A D|$.

S10: (supplement axiom) If two angles form a linear pair, then they are supplementary.
S11: $(S A S)$ If $A B \equiv A^{\prime} B^{\prime}, B C \equiv B^{\prime} C^{\prime}$, and $\angle B \equiv \angle B^{\prime}$ then $\triangle A B C \equiv \triangle A^{\prime} B^{\prime} C^{\prime}$.
S12: (parallel axiom) Through any point not on a given line there is exactly one line that is parallel to the given line.

S13: (area axiom) To every polygon corresponds a unique positive real number.
S14: (congruence preserves area) If two triangles are congruent they have the same area.
S15: (areas addition) If two regions intersect in at most a finite number of segments and points, then the area of their union is the sum of their areas.

S16: (area of a rectangle axiom) The area of a rectangle is the product of the length of two of its sides that share a vertex.

Euclidean Plane Geometry Definitions - Quick Reference

| Definition | is equivalent to |
| :---: | :---: |
| $(\mathcal{P}, \mathcal{L})$ is an incidence structure | $\mathcal{L}$ is a set of subsets of $\mathcal{P}$ |
| $A$ is a point | $A \in \mathcal{P}$ where $(\mathcal{P}, \mathcal{L})$ is an incidence structure |
| $l$ is a line | $l \in \mathcal{L}$ where $(\mathcal{P}, \mathcal{L})$ is an incidence structure |
| $F$ is a figure | $F \subseteq \mathcal{P}$ where $(\mathcal{P}, \mathcal{L})$ is an incidence structure |
| figure $F$ is collinear | $F \subseteq l$ for some line $l$ |
| lines $l, m$ are parallel | $l \cap m=\emptyset$ |
| $l \\| m$ | $l$ is parallel to $m$ |
| $C$ is the parallel class of $l$ | $C=\{m: m \\| l$ or $m=l\}$ |
| $P$ is the pencil of lines through point $A$ | $P=\{m: A \in m\}$ |
| $\mathbb{E}$ is a Euclidean Plane | $\mathbb{E}$ is an incidence structure satisfying axioms S1-S16 |
| $\|A B\|$ is the distance from $A$ to $B$ | $\|A B\|$ is the unique positive number assigned to the distinct pair of points $A, B$ in axiom S 2 |
| $\|A A\|$ is the distance from $A$ to $A$ | $\|A A\|=0$ |
| $\Psi_{l}$ is a coordinate system | $\Psi_{l}: l \rightarrow \mathbb{R}$ is a bijection and $l$ is a line |
| $x$ is the coordinate of point $A$ | $x=\Psi_{l}(A)$ |
| $B$ is between $A$ and $C$ | points $A, B, C$ are collinear and $\|A B\|+\|B C\|=\|A C\|$ |
| A.B.C | $B$ is between $A$ and $C$ |
| $A B$ is a segment | $A B=\{P: A . P . B\} \cup\{A, B\}$ |
| $\overrightarrow{A B}$ is a ray | $\overrightarrow{A B}=\{P: A . B . P\} \cup A B$ |
| $x$ is an endpoint or vertex of $A B$ | $x=A$ or $x=B$ |
| $x$ is an endpoint or vertex of $\overrightarrow{A B}$ | $x=A$ |
| $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are opposite rays | C.A.B |
| $M$ is the midpoint of $A B$ | $A . M . B$ and $\|A M\|=\|M B\|$ |
| $F$ is a convex figure | for all $A, B$ in $F, A B \subseteq F$ |
| $L, R$ are half planes with edge $l$ | $L, R$ are the disjoint sets of points not the line $l$ given by axiom S6 |
| $A, B$ are on the same side of $l$ | $A, B$ are in the same half plane formed by $l$ |
| $A, B$ are on the opposite side of $l$ | $A, B$ are different half planes formed by $l$ |
| $\angle A B C$ is an angle | $\angle A B C=\overrightarrow{B A} \cup \overrightarrow{B C}$ |
| $x$ is the vertex of $\angle A B C$ | $x=B$ |

## Euclidean Plane Geometry Definition - Quick Reference (cont)

## Definition

is equivalent to

| $\triangle A B C$ is a triangle | $A, B, C$ are distinct, not collinear, and $\triangle A B C=A B \cup B C \cup C A$ |
| :--- | :--- |
| $\triangle A B C$ is a degenerate triangle | $A, B, C$ are collinear |
| $P$ is in the interior of $\angle B A C$ | $P$ is on the same side of $\overrightarrow{A B}$ as $C$ and |
| $P$ is in the exterior of $\angle B A C$ | $P$ is on the same side of $\overrightarrow{A C}$ as $B$ |
| $\angle B A D$ and $\angle C A D$ are a linear pair | $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are opposite rays and $D$ is not on $\overleftrightarrow{B C}$ |
| $\angle A, \angle B$ are supplementary | $\|\angle A\|+\|\angle B\|=180$ |
| $\angle A, \angle B$ are complementary | $\|\angle A\|+\|\angle B\|=90$ |
| $\angle A$ and $\angle B$ are right angles | $\angle A, \angle B$ are a linear pair and $\|\angle A\|=\|\angle B\|$ |
| 2 collinear figures are perpendicular | the lines containing the figures determine a right angle |
| $l$ is a perpendicular bisector of $A B$ | $l$ contains the midpoint of $A B$ and is perpendicular to $A B$ |
| $\angle A$ is congruent to $\angle B$ | $\|\angle A\|=\|\angle B\|$ |
| $A B$ is congruent to $C D$ | $\|A B\|=\|C D\|$ |

$\triangle A B C$ is congruent to $\triangle A^{\prime} B^{\prime} C^{\prime}$
$\exists \xi:\{A, B, C\} \rightarrow\left\{A^{\prime}, B^{\prime}, C^{\prime}\right\}$ a bijection such that
$A B \equiv \xi(A) \xi(B), B C \equiv \xi(B) \xi(C), A C \equiv \xi(A) \xi(C)$,
$\angle A \equiv \angle \xi(A), \angle B \equiv \angle \xi(B)$, and $\angle C \equiv \angle \xi(C)$

|  | $A_{1} A_{2} A_{3} \cdots A_{n}=\left(\cup_{i=1}^{n-1} A_{i} A_{i+1}\right) \cup A_{1} A_{n}$ and |
| :--- | :--- |
| $A_{1} A_{2} A_{3} \cdots A_{n}$ is a polygon | these segments intersect only at their endpoints |
|  | and no intersecting segments are collinear |
| $\left[A_{1} A_{2} A_{3} \cdots A_{n}\right]$ is the area | $\left[A_{1} A_{2} A_{3} \cdots A_{n}\right]$ is the real number given by axiom S12 |

## Review of Elementary Plane Euclidean Geometry

## Some common definitions

## Angles

- obtuse angle: an angle whose measure is greater than 90
- acute angle: an angle whose measure is less than 90
- adjacent angles: two angles that share a common ray
- transversal: a line $k$ that intersects two other lines $l, m$ at one point. The various pairs of the eight angles formed by $k$ with $l$ and $m$ are:


Figure 1

- alternate interior angles: $\{4,5\},\{3,6\}$
- alternate exterior angles: $\{2,7\},\{1,8\}$
- same side interior angles: $\{3,5\},\{4,6\}$
- same side exterior angles: $\{1,7\},\{2,8\}$
- corresponding angles: $\{1,5\},\{3,7\},\{2,6\},\{4,8\}$
- vertical angles: $\{1,4\},\{2,3\},\{5,8\},\{7,6\}$
- adjacent angles: $\{1,3\},\{3,4\},\{4,2\},\{1,2\},\{5,7\},\{7,8\},\{8,6\},\{5,6\}$


## Triangles

- isosceles triangle: a triangle with two congruent angles
- equilateral triangle: a triangle with three congruent sides
- scalene triangle: a triangle in which no two sides are congruent
- obtuse triangle: a triangle containing an obtuse angle
- acute triangle: a triangle containing an acute angle
- right triangle: a triangle containing a right angle
- legs: the sides forming the right angle in a right triangle
- hypotenuse: side opposite the right angle in a right triangle
- exterior angle: the angle formed by the opposite ray of the ray containing one side of a triangle (or polygon) and the side of the triangle (or polygon) that shares the same vertex
- degenerate triangle: $A B \cup B C \cup A C$ when $A, B, C$ are collinear (note that a degenerate triangle is not actually a triangle, but rather is thought of as what you would get if the three vertices of a triangle were moved continuously to become collinear).


## Cevians and Related Segments

- cevian: any line segment joining a vertex of a triangle to a point on the opposite side other than the vertices
- altitude: the perpendicular segment from a vertex of a triangle to the line containing the opposite side. Also any segment connecting the line containing one side of a parallelogram or trapezoid to the line containing the opposite side that is perpendicular to both lines
- base: given an altitude or cevian of a triangle, the base of the triangle is the side opposite to the vertex containing the altitude or cevian. We say that the base and altitude/cevian correspond to each other. Similarly the vertex contained by the cevian or altitude is called its vertex. Also the parallel sides in a trapezoid are called its bases.
- distance between parallel lines: is the length of any segment that is connects a point on one line to a point on a line parallel to it and is perpendicular to both sides (see SMSG Thm 53 below).
- median: a cevian connecting a vertex to the midpoint of the opposite side
- angle bisector: a ray containing a point in the interior of an angle that bisects the angle (i.e. an angle bisector of $\angle A B C$ is a ray $\overrightarrow{A D}$ such that $D$ is in the interior of $\angle A B C$ and $\angle A B D \equiv \angle D B C)$. Also the cevian contained in the angle bisector of the angle of a triangle, or the line containing the angle bisector of an angle.
- foot: the foot of a cevian or altitude is the point where it meets the line containing the side opposite its vertex. Given a point $P$ not on a line $l$ the foot of the perpendicular line from $P$ to $l$ is the point where that line intersects $l$. If $P$ is on $l$, the foot of the perpendicular through $P$ to $l$ is $P$ itself.
- parallel collinear figures: two figures, each of which is a subset of a line, are parallel if the two lines containing the figures are parallel


## Polygons

- quadrilateral: a polygon with exactly four sides
- trapezoid: a quadrilateral with exactly one pair of parallel sides
- isosceles trapezoid: a trapezoid having two angles that share one of the sides in the parallel pair
- parallelogram: a quadrilateral with two pairs of parallel sides
- rectangle: a quadrilateral with four congruent angles
- rhombus: a quadrilateral with four congruent sides
- square: a quadrilateral that is both a rectangle and a rhombus
- pentagon: a polygon with five sides
- hexagon: a polygon with six sides
- heptagon: a polygon with seven sides
- octagon: a polygon with eight sides
- nonagon: a polygon with nine sides
- decagon: a polygon with ten sides
- regular polygon: a polygon with $n$ sides having all sides and all angles congruent


## Circles

- circle: a figure consisting of all points that are a fixed positive distance $r$ from a given
point $O$. We if $A$ is a point on the circle with center $O$ and radius $r$ we designate this circle as $\odot O A$ and write $|\odot O A|=r$.
- center: the point $O$ in the definition of a circle
- radius: any segment having the center and a point on the circle as endpoints. The length of any radius is also referred to as the radius of the circle
- circle congruence: two circles are congruent if and only if their radii are the same length. Every circle is congruent to itself.
- chord: a segment connecting two distinct points on a circle
- diameter: a chord that contains the center. The length of any diameter is also called the diameter of the circle.
- tangent: a line that intersects a circle at exactly one point
- tangent circles: two circles that intersect at exactly one point
- central angle: an angle whose vertex is the center of a given circle
- arc: the set of points on a circle that are in the interior of or on a central angle or the set of points on a circle that are in the exterior of or on a central angle
- measure of an arc: the measure of the corresponding central angle if the arc is in the interior of the central angle and 360 minus the measure of the central angle otherwise


## Similarity

- similar triangles: Two triangles are similar if and only if there is a correspondence between them such that the corresponding angles are congruent and lengths of the corresponding sides are proportional. If $\triangle A B C$ is similar to $\triangle D E F$ we write $\triangle A B C \sim \triangle D E F$.

Remark Sometimes we will refer to a segment and its length interchangeably when there can be no possiblility of confusion from context. For example we might say that the area of a triangle is half the product of an altitude and the corresponding base instead of saying that it is half the product of the length of an altitude and the length of the corresponding base. However we must take care when using this in situations where it might be ambiguous, for example, saying that two triangles have altitudes of equal length is not the same as saying that two triangles have equal altitudes (i.e. equal as sets of points).

## Review of Some Elementary Theorems

The following list of theorems are numbered so we can reference them by number as we need them in the course. If the number is followed by a phrase in parentheses, that denotes the name of the theorem. We should refer to a theorem by name whenever a name is available and use the number when no name is available. When referencing these theorems in your proofs refer to them as, e.g. SMSG Thm 4 to distinguish them from other proofs we prove in this course.

## * proven for homework

## Thm

1.     * Every line contains infinitely many points.
2.     * The Euclidean plane is an affine plane.
3.     * ( $\equiv$ is an equivalence relation) Congruence of segments (respectively angles) is an equivalence relation on the set of all segments (respectively angles).
4.     * If $l, m$ are distinct lines and $F \subseteq l$ and $G \subseteq m$ then $F$ and $G$ intersect in at most one
point. (so for example, if $F$ and $G$ are segments or rays they can intersect in at most one point).
5. If $A . B . C$ then $C . B . A$.
6. (order thm) Let $A, B, C$ be three distinct collinear points and $\Psi$ a coordinate system for the line containing them. Then

$$
\Psi(A)<\Psi(B)<\Psi(C) \text { or } \Psi(C)<\Psi(B)<\Psi(A) \Leftrightarrow A . B . C
$$

7.     * If $A . B . C$ and B.C.D then A.B.D and A.C.D.
8.     * If $A, B, C$ are distinct collinear points then exactly one of the three statements $A . B . C$, $B . A . C, A . C . B$ is true.
9.     * (point plotting thm) For any ray $\overrightarrow{A B}$ and positive real number $r$, there exists exactly one point $P$ on $\overrightarrow{A B}$ such that $|A P|=r$. In particular, we can extend any segment to any length in either direction.
(corollary) If $C D$ is a segment and $\overrightarrow{A B}$ a ray there is a unique point $P$ on $\overrightarrow{A B}$ such that $A P \equiv C D$.
10. Midpoints exist and are unique.
11.     * If $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are opposite rays then $\overrightarrow{A B} \cup \overrightarrow{A C}=\overleftrightarrow{B C}$ and $\overrightarrow{A B} \cap \overrightarrow{A C}=\{A\}$.
12.     * Every point $A$ on $l$ divides the points other than $A$ on $l$ into two disjoint convex sets $L$ and $R$ such that for any $P \in L$ and $Q \in R$ the segment $Q P$ contains $A$. (point plotting thm) If $l, m$ are distinct lines that meet at $A$ and $r$ is a positive real number then $m$ has points on both sides of $l$ that are distance $r$ from $A$ (and similarly if $C D$ is a given segment there are points $P, P^{\prime}$ on $m$ on opposite sides of $l$ such that $\left.A P \equiv A P^{\prime} \equiv C D\right)$.
13.     * If a line $l$ intersects two sides of a triangle at points between the vertices, then $l$ does not intersect the third side of the triangle.
14.     * (ray-half plane) If $l$ is any line containing $A$, and $B$ is not on $l$, then all points on the ray $\overrightarrow{A B}$ except $A$ are on the same side of $l$ as $B$.
15. (Pasch) If $l$ meets side $A C$ in $\triangle A B C$ at exactly one point between $A$ and $C$ then $l$ intersects $A B$ or $B C$.
16. (crossbar) If $D$ is in the interior of $\angle A$ in $\triangle A B C$ then $\overrightarrow{A D}$ intersects $B C$.
17.     * In any triangle $\triangle A B C$ every point between $B$ and $C$ is in the interior of $\angle A$.
18. (SOCAC) Supplements of the same or congruent angles are congruent.
19.     * (COCAC) Complements of the same or congruent angles are congruent.
20.     * Vertical angles are congruent.
21.     * (right angles are 90) All right angles are congruent. An angle is a right angle if and only if it has measure 90 .
22.     * If $l, m$ intersect at one point and one of the four angles formed is a right angle then all four angles are right angles.
23. $(A S A)$ If $\angle A \equiv \angle D, A B \equiv D E, \angle B \equiv \angle E$ then $\triangle A B C \equiv \triangle D E F$.
24. (isosceles $\triangle$ ) Two sides in a triangle are congruent if and only if the angles opposite those sides are congruent.
25.     * A triangle is equilateral if and only if it is equilangular.
26. Angle bisectors exist and are unique.
27. $(S S S)$ If $A B \equiv D E, B C \equiv E F, A C \equiv D F$ then $\triangle A B C \equiv \triangle D E F$.
28. (uniqueness of perpendiculars) Through a given point there exists exactly one line perpendicular to a given line.
29.     * (right triangle) At most one angle of a triangle can be a right angle.
30.     * (perpendicular bisector) A point $P$ is equidistant from two distinct points $A, B$ if and only if $P$ is on the perpedicular bisector of $A B$.
31. (exterior angle) The measure of an exterior angle of a triangle is greater than the measure of either of the two opposite angles.
32. $(A A S)$ If $\angle A \equiv \angle D, \angle B \equiv \angle E$, and $B C \equiv E F$ then $\triangle A B C \equiv \triangle D E F$.
33.     * $(H L)$ If the hypotenuse and leg of one right triangle are congruent, respectively, to the hypotenuse and leg of another, then the right triangles are congruent.
34. (big angle, big side) In $\triangle A B C,|\angle A|>|\angle B|$ if and only if $a>b$ (i.e. $|B C|>|A C|$ ).
35.     * (point to line distance) The shortest segment joining a point to a line is the perpendicular segment.
36. (triangle inequality) The sum of the lengths of two sides of a triangle is greater than the length of the third side.
37.     * (bigger angle, bigger side) If two sides of one triangle are congruent respectively to two sides of a second triangle, then the included angle of the first is larger than the included angle of the second if and only if the remaining side of the first is longer than the remaining side of the second.
38.     * (common perpendicular) Two distinct lines that are perpendicular to the same line are parallel.
39. (alternate interior angle) If two lines are cut by a transversal then the two lines are parallel if and only if the alternate interior angles formed are congruent.
40.     * (corresponding angles) If two lines are cut by a transversal then the two lines are parallel if and only if any pair of corresponding angles formed are congruent. In this situation all pairs of corresponding angles are congruent.
41.     * (same side interior angles) If two lines are cut by a transversal then the two lines are parallel if and only if any pair of same side interior angles formed are supplementary. In this situation both pairs of same side interior angles formed are supplementary.
42.     * Two distinct lines parallel to the same line are parallel to each other.
43.     * (parallel class) The set of all parallel classes is a partition of the set of all lines.
44.     * (common perpendicular) If line $l$ is perpendicular to line $m$ then $l$ is perpendicular to all lines in the parallel class of $m$.
45. $(\triangle$ sum $)$ The sum of the measures of the angles in a triangle is 180 .
46.     * (exterior angle) The measure of an exterior angle of a triangle is equal to the sum to the measures of the angles of the triangle that are not adjacent to it.
47.     * (parallelogram) Either diagonal of a parallelogram divides it into two congruent triangles. Any pair of parallel sides in a parallelogram are congruent. The opposite angles are congruent and consecutive angles are supplementary. The diagonals of a parallelogram bisect each other.
48.     * (distance between parallels) If $l \| m$ and $P, Q$ are on $l$ then the distance from $P$ to $m$
and
the distance from $Q$ to $m$ are equal.
49.     * (parallelogram) If both pairs of opposite sides in a quadrilateral are congruent, then the quadrilateral is a parallelogram.
50.     * (parallelogram) If two sides of a quadrilateral are parallel and congruent then the quadrilateral is a parallelogram.
51.     * (rectangle) If a parallelogram has a right angle then it is a rectangle.
52.     * (rhombus) The diagonals of a parallelogram are perpendicular if and only if the parallelogram is a rhombus.
53.     * (parallel projection) Let $A, B, C$ be distinct points on line $l$ with $A . B . C$ and $A^{\prime}, B^{\prime}, C^{\prime}$ points on $m$ such that $A A^{\prime}\left\|B B^{\prime}\right\| C C^{\prime}$ then $A^{\prime} . B^{\prime} . C^{\prime}$.
54. (parallel projection) Let $A, B, C, D$ be distinct points on line $l$ with $A B \equiv C D$ and $A^{\prime}, B^{\prime}, C^{\prime}, D^{\prime}$ points on $m$ such that $A A^{\prime}\left\|B B^{\prime}\right\| C C^{\prime} \| D D^{\prime}$ then $A^{\prime} B^{\prime} \equiv C^{\prime} D^{\prime}$.
55.     * (equidistant parallels) If three parallel lines intercept congruent segments on one transversal then they intercept congruent segments on every transversal.
56.     * (midpoint connector) Let $\triangle A B C$ be a triangle and $M, N$ the midpoints of $A B$ and $A C$ respectively. Then $M N \| B C$ and $|M N|=\frac{1}{2}|B C|$.
57.     * (area of a right triangle) The area of a right triangle is half the product of the lengths of its legs.
58. (area of a triangle) The area of a triangle is half of the product of an altitude and its corresponding base.
59.     * (area of a parallelogram) The area of a parallelogram is the product of one side and the distance from that side to the side parallel to it.
60.     * (area of a trapezoid) The area of a trapezoid is the product of the average of the lengths of its bases and the distance between the bases.
61.     * If two triangles have altitudes of the same length, the ratio of their areas is the same as the ratio of the lengths of the sides opposite the vertex containing their altitudes.
62.     * Two triangles having equal length altitudes and corresponding bases have equal area.
63. (Pythagorean Theorem) In any right triangle the square of the length of the hypotenuse is equal to the sum of the squares of the lengths of the legs.
64.     * (converse of the Pythagorean Theorem) In any triangle if the square of the length of the one side is equal to the sum of the squares of the other two sides then the triangle is a right triangle with right angle opposite the longest side.
65.     * (30-60-90 triangle) A $\triangle A B C$ has $|\angle A|=90,|\angle B|=60$ (and thus $|\angle C|=30$ ) if and only if $|B C|=2|A B|$ and $|A C|=\sqrt{3}|A B|$.
66.     * (isosceles right triangle) A right triangle is isosceles if and only if the ratio of the length of the hypotenuse to the length of a leg is $\sqrt{2}$.
67. (basic proportionality) A segment connecting points on two sides of a triangle is parallel to the third side if and only if the segments it cuts off are proportional to the sides.
68.     * $(A A)$ If two triangles have two congruent corresponding angles then the triangles are similar.
69.     * (basic proportionality) A line parallel to a side of a triangle that intersects the two other sides at distinct points cuts off a triangle that is similar to the original triangle.
70.     * (similarity $S A S$ ) If $\angle A \equiv \angle D$ and $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}$ then $\triangle A B C \sim \triangle D E F$.
71. (similarity SSS) If $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}=\frac{|B C|}{|E F|}$ then $\triangle A B C \sim \triangle D E F$.
72.     * (altitude to the hypotenuse) In any right triangle the altitude to the hypotenuse separates the triangle into two smaller triangles which are similar to each other and the original triangle.
73. (fundamental theorem for circles) Let $l$ be a line, $\odot O A$ a circle, and $F$ the foot of the perpendicular to $l$ through $O$. Then either
(a) Every point of $l$ is outside the circle, or
(b) $F$ is on the circle and every other point of $l$ is outside the circle (and thus $l$ is a tangent line), or
(c) $F$ is inside the circle and $l$ intersects the circle in two points which are equidistant from $F$.
74.     * (tangent line) A line $l$ through point $A$ is tangent to $\odot O A$ at $A$ if and only if $O A \perp l$.
75.     * (chord) In any circle, a radius bisects a chord if and only if the radius is perpendicular to the chord, and the perpendicular bisector of any chord contains the center.
76.     * (circle cutting) Any line that contains a point in the interior of a circle intersects the circle in two points.
77.     * (chord congruence) Two chords in the same or congruent circles are congruent if and only if they are the same distance from the center of the circle containing them.
78. (Two Circle Theorem) If two circles having radii $a$ and $b$ have centers that are a distance $c$ apart, and if each of $a, b, c$ is less than the sum of the other two, then the two circles intersect at exactly two points, one on each side of the line through their centers.
79. (triangle existance) For any positive real numbers $a, b, c$ such that the sum of any two is greater than the third there is a triangle $\triangle A B C$ having side lengths $a, b, c$.
80.     * (tangent circles) If two distinct circles having radii $a$ and $b$ have centers that are a distance $c$ apart, then the two circles intersect at exactly one point if and only if the largest of $a, b, c$ is equal to the sum of the other two. In this situation the point of intersection lies on the line through the centers.
81.     * (disjoint circles) If two circles having radii $a$ and $b$ have centers that are a distance $c$ apart, then the two circles do not intersect if and only if the largest of $a, b, c$ is greater than the sum of the other two.

## Further Study of Euclidean Plane Geometry

## Angles Intercepting Circles

We now begin our study of some of the more advanced topics of Euclidean geometry given in the textbook. Note that the author assumes that we have an understanding of trigonometry and also allows us to determine betweenness relationships from diagrams rather than proving them from the separation axiom. However care must be taken to avoid errors in proofs obtained by taking this shortcut.
Theorem (Star Trek Lemma) The measure of an angle inscribed in a circle is half of the measure of the arc it subtends.

Corollary If triangle $\triangle A B C$ is inscribed in a circle then $\angle A$ is a right angle if and only if
$B C$ is a diameter.
Corollary (Bow Tie Lemma) Two inscribed angles that subtend the same arc are congruent.
Theorem (Tangential Case of Star Trek Lemma) If AT is tangent to circle $\odot O T$ at $T$ and $B$ is another point on $\odot O T$ then the measure of $\angle A T B$ is half of the measure of the arc it subtends.

Theorem (interior Star Trek Lemma) If chords $A A^{\prime}$ and $B B^{\prime}$ meet at a point $P$ in the interior of $\odot O A$ and the measures of the minor arcs $A B$ and $A^{\prime} B^{\prime}$ are $\alpha$ and $\beta$ respectively, then

$$
|\angle A P B|=\frac{\alpha+\beta}{2}
$$

Theorem (exterior Star Trek Lemma) If chords $A A^{\prime}$ and $B B^{\prime}$ are extended to meet at a point $P$ in the exterior of $\odot O A$ so that $P . A^{\prime} . A$ and $P . B^{\prime} . B$ and the measures of the minor arcs $A B$ and $A^{\prime} B^{\prime}$ are $\alpha$ and $\beta$ respectively, then

$$
|\angle A P B|=\frac{\alpha-\beta}{2}
$$

## Similarity

Remark Baragar defines two triangles to be similar if they have corresponding angles that are congruent in pairs, so his definition is slightly different than ours. However, in Euclidean geometry the two definitions are equivalent by the AA theorem.

Recall SMSG theorem 67:
Theorem (basic proportionality) A segment connecting points on two sides of a triangle is parallel to the third side if and only if the segments it cuts off are proportional to the sides.

Lemma (fun with fractions) Let $a, b, x, y$ be real numbers with $y, b, y-b$, and $y+b$ nonzero. Then

$$
\frac{x}{y}=\frac{a}{b} \Rightarrow \frac{x}{y}=\frac{a}{b}=\frac{x-a}{y-b}=\frac{x+a}{y+b}
$$

Theorem (Angle Bisector Theorem) If $D$ is the point where the angle bisector of $\angle A$ in $\triangle A B C$ meets $B C$ then

$$
\frac{|B D|}{|B A|}=\frac{|C D|}{|C A|}
$$

Also recall SMSG Thm 68,70,71
Theorem (AA) If two triangles have two congruent corresponding angles then the triangles are similar.

Theorem (similarity SAS) If $\angle A \equiv \angle D$ and $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}$ then $\triangle A B C \sim \triangle D E F$.
Theorem (similarity SSS) If $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}=\frac{|B C|}{|E F|}$ then $\triangle A B C \sim \triangle D E F$.

## Power of a Point

Theorem (power of a point) Let $\odot O A$ be a circle and $P$ a point not on the circle. Then for every line l through $P$ that meets the circle in two points $Q, R$ the product

$$
|P Q| \cdot|P R|
$$

has the same value.

Definition Let $\odot O A$ be a circle and $P$ a point. Define $\Pi(P)=|O P|^{2}-r^{2}$ where $r=|O A|$.

Corollary Let $\odot O A$ be a circle and P a point. Then the value of the product given in the previous theorem is $\Pi(P)$ if $P$ is outside or on the circle and $-\Pi(P)$ if $P$ is inside the circle.

Remark Note that $\Pi(P)$ is zero if $P$ is on the circle, which is the degenerate case of the power of a point theorem in which all of the products are zero.

Theorem (tangential version of power of a point) Let $\odot O A$ be a circle, $P$ a point in the exterior of the circle, and $\overleftrightarrow{P Q}$ a tangent line to the circle meeting the circle at $Q$. Then

$$
|P Q|^{2}=\Pi(P)
$$

Remark Thus the tangential version can be thought of as a special case of the power of a point theorem where we have $Q=R$.

## Ceva' Theorem

Theorem Let $D, E, F$ be three points, respectively, on sides $B C, A C$, and $A B$ of $\triangle A B C$. Then $A D, B E$, and $C F$ are concurrent at a point $P$ if and only if

$$
\frac{|B D|}{|C D|} \cdot \frac{|C E|}{|A E|} \cdot \frac{|A F|}{|B F|}=1
$$

## Medians and Centroid

Definition Let $\triangle A B C$ be a triangle and $A^{\prime}, B^{\prime}, C^{\prime}$ the midpoints of sides $B C, A C$, and $A B$ respectively. The cevians $A A^{\prime}, B B^{\prime}$ and $C C^{\prime}$ are called the medians of the triangle.

Theorem The medians of a triangle are concurrent.

Definition The intersection of the medians of a triangle is called the centroid of the triangle and is usually denoted by the letter $G$.

## Recall SMSG Thm 56,

Theorem (midpoint connector) Let $\triangle A B C$ be a triangle and $M, N$ the midpoints of $A B$ and $A C$ respectively. Then $M N \| B C$ and $|M N|=\frac{1}{2}|B C|$.

Theorem The medians of a triangle intersect at a point $2 / 3$ of the way from the vertex to the midpoint of the opposite side. In other words, if $G$ is the centroid of $\triangle A B C$ and $A^{\prime}, B^{\prime}$, and $C^{\prime}$ are the midpoints of the sides $B C, A C$, and $A B$ respectively, then $|A G|=2\left|G A^{\prime}\right|$, $|B G|=2\left|G B^{\prime}\right|$, and $|C G|=2\left|G C^{\prime}\right|$.

## Incircle and Excircles

Lemma A point $P$ is equidistant from two distinct lines $l, m$ that intersect at $A$ if and only if is on an angle bisector of one of the angles formed by the lines at point $A$.

Theorem The angle bisectors of the angles of a triangle are concurrent.

Definition The point of intersection of the angle bisectors of the angles of a triangle is called the incenter and is usually denoted by the letter I.

Corollary The incenter is the unique point that is equidistant from the three sides of a triangle.

Definition Let $r$ be the distance from the incenter I to the sides of $\triangle A B C$. The circle centered at I with radius $r$ is called the incircle of the triangle.

Remark By the Fundamental Theorem of Circles the incircle is tangent to all three sides of the circle.

Theorem The external angle bisectors of the angles of a triangle $\triangle A B C$ intersect at points $I_{A}, I_{B}$, and $I_{C}$ which are respectively on the angle bisectors of angles $A, B$ and $C$. These three points are also equidistant from the lines containing the three sides of the triangle.

Definition The points $I_{A}, I_{B}, I_{C}$ are called excenters of $\triangle A B C$. They are the centers of three circles that are tangent to all three lines containing the sides of $\triangle A B C$. These circles are called the excircles, and their radii are called the exradii and denoted $r_{A}, r_{B}, r_{C}$ respectively.

## Area, Inradius, Exradif

Definition If $\triangle A B C$ has sides of length $a, b, c$ then the semiperimeter of the triangle is

$$
s=\frac{a+b+c}{2}
$$

Theorem * (Vertex to incircle) If $\triangle A B C$ has sides of length $a, b, c$, semiperimeter $s$, and $P$ is the point where the incircle meets $A B$ then $|A P|=s-a$.

Theorem * (Vertex to excircle) If $\triangle A B C$ has sides of length $a, b, c$, semiperimeter s and exradius $r_{A}$ and $Q$ is the point where the excircle corresponding to $A$ meets $A B$ then $|A Q|=s$ and $|B Q|=s-c$.

Theorem If $\triangle A B C$ has semiperimeter $s$ and inradius $r$ then

$$
|\triangle A B C|=r s
$$

Theorem * If $\triangle A B C$ has sides of length $a, b, c$, semiperimeter $s$ and exradii $r_{A}, r_{B}, r_{C}$ then

$$
|\triangle A B C|=r_{A}(s-a)=r_{B}(s-b)=r_{C}(s-c)
$$

## Heron's Formula

Theorem (Heron's Formula) In any triangle $\triangle A B C$,

$$
|\triangle A B C|=\sqrt{s(s-a)(s-b)(s-c)}
$$

where $s=(a+b+c) / 2$.

## Orthocenter

Theorem * The lines containing the three altitudes of a triangle are concurrent.

Definition The point of intersection of the lines containing the altitudes of a triangle is called the orthocenter and is usually denoted by the letter $H$.

## Circumcircle, Circumcenter, Circumradius

Recall SMSG Thm 30:
Theorem * (perpendicular bisector) A point $P$ is equidistant from two distinct points $A, B$ if and only if $P$ is on the perpedicular bisector of $A B$.

Theorem (circumcenter exists) The perpendicular bisectors of the three sides a triangle are concurrent.

Definition The point of intersection of the perpendicular bisectors of the sides of a triangle is called the circumcenter and is usually denoted by the letter $O$.

Corollary The circumcenter is the unique point that is equidistant from the three vertices of
a triangle.

Definition Let $O$ be the circumcenter of $\triangle A B C$. Then $\odot O A$ is called the circumcircle of $\triangle A B C$ and the length of its radius is called the circumradius and denoted $R$.

## Extended Law of Sines

Theorem (Extended Law of Sines) In any triangle $\triangle A B C$

$$
\frac{a}{\sin (A)}=\frac{b}{\sin (B)}=\frac{c}{\sin (C)}=2 R
$$

where $R$ is the circumradius.

## Law of Cosines

Theorem (Law of Cosines) In any triangle $\triangle A B C$,

$$
c^{2}=a^{2}+b^{2}-2 a b \cos (|\angle C|)
$$

## Stewart's Theorem

Theorem (Stewart) If AP is a cevian of $\triangle A B C$ and $|A P|=l,|B P|=m,|C P|=n$ then

$$
a\left(l^{2}+m n\right)=b^{2} m+c^{2} n
$$

## Cyclic Quadrilaterals and Ptolemy's Theorem

Definition A quadrilateral is cyclic if it can be inscribed in a circle.

Remark Since any three vertices of a quadrilateral can be circumscribed by a circle, the quadrilateral is cyclic if and only if the fourth vertex is on the circumcircle of the triangle formed by the other three vertices. Also, since the circumcircle of a triangle is unique, so is the circumcircle of a cyclic quadrilateral (because if there were two there would be two circumcircles for the triangle formed by three of the vertices).

Theorem * A quadrilateral is cyclic if and only if its opposite angles are supplementary.

Theorem (Ptolemy's Theorem) $\square A B C D$ is a cyclic quadrilateral if and only if

$$
|A C||B D|=|A B \| C D|+|A D||B C|
$$

## More Fun with Triangles

## The Euler Line

Theorem The circumcenter, orthocenter, and centroid of a triangle are collinear.

Definition The line containg the circumcenter, orthocenter and centroid is called the Euler Line.

Theorem In $\triangle A B C$ we have H.G.O and $|H G|=2|G O|$ (where $H$ is the orthocenter, $G$ is the centroid, and $O$ is the circumcenter as usual).

Remark We often refer to the line segment HO as the Euler line even though it is technically a segment, not a line.

## The Nine Point Circle

Theorem In any triangle, the midpoints of the sides, the feet of the altitudes, and the midpoints of the segments connecting the vertices to the orthocenter are all contained in a circle whose center is the midpoint of the Euler line.

## Pedal Triangles

Definition Let $P$ be a point and $\triangle A B C$ a triangle. Let $X, Y, Z$ be the feet of the perpendiculars through $P$ to $\overleftrightarrow{A B}, \overleftrightarrow{B C}$, and $\overleftrightarrow{A C}$ respectively. Then $\triangle X Y Z$ is called the pedal triangle with repect to $P$ and $\triangle A B C$.

Theorem (Simson line) The pedal triangle with respect to $P$ and $\triangle A B C$ is degenerate if and only if $P$ is on the circumcircle of $\triangle A B C$.

Definition When the pedal triangle is degenerate, the line through $X, Y$, and $Z$ is called the Simson line.

Theorem The pedal triangle of the pedal triangle of the pedal triangle with respect to $a$ point $P$ is similar to the original triangle.

## Menelaus Theorem

> Definition Let $A$ and $B$ be distinct points and $\Psi$ a coordinate system on $\overleftrightarrow{A B}$ with $\Psi(A)=0$ and $\Psi(B)>0$. Then for any points $C, D$ we define the signed length of the segment $C D$ to be $|C D|$ if $\Psi(C)<\Psi(D)$ and $-|C D|$ if $\Psi(D)<\Psi(C)$. We denote the signed length of $C D$ (with respect to this coordinate system) as $\|C D\|$.

Remark Notice that $\|C D\|=-\|D C\|$ for any choice of coordinate system.
Theorem (Menelaus) Let D, E,F be three points on, respectively, the lines $\overleftrightarrow{B C}, \overleftrightarrow{A C}$, and $\overleftrightarrow{A B}$ containing the sides of $\triangle A B C$. Then $D, E, F$ are collinear if and only if

$$
\frac{\|A F\|}{\|F B\|} \frac{\|B D\|}{\|D C\|} \frac{\|C E\|}{\|E A\|}=-1
$$

Remark The signed lengths in the previous theorem are independent of the coordinate systems chosen, but all segments on the same line must use the same choice of coordinate system.

## The Gergonne Point

Theorem The cevians from the vertices to the points of intersection of the incircle with the sides of a triangle are concurrent.

## Definition The point of concurrency in the previous theorem is called the Gergonne point.

## The Nagel Point

Theorem The cevians from the vertices to the points of intersection of the three excircles with the sides of a triangle are concurrent.

Definition The point of concurrency in the previous theorem is called the Nagel point.

## Morley's Theorem

Theorem (Morley) The points of intersection of consecutive angle trisectors of the angles of a triangle are the vertices of an equilateral triangle.

## Contructions with Straightedge and Compass

Definition Let $O$ and $A$ be distinct points. The following figures and points are constructible.

1. $O$ and $A$ are constructible.
2. If $X, Y$ are distinct constructible points then the line $\overleftrightarrow{X Y}$ is constructible.
3. If $X, Y$ are distinct constructible points then the circle $\odot X Y$ is constructible.
4. Iff, $g$ are distinct constructible figures (i.e. circles or lines), then their points of intersection are constructible.
5. All constructible figures are obtained by a finite number of applications of rules \#1-4.

Remark A more general definition of constructible can be obtained by replacing $\{O, A\}$ in the previous definition with another set of given constructible points S. In this case we can say that the points, lines, and circles are constructible from $S$. However, unless otherwise stated we will always use the term 'constructible' to mean 'constructible from $\{O, A\}$ with $|O A|=1$.

Remark We also say that a segment, ray, triangle, etc is constructible if the points that define it are constructible. For example, $\overrightarrow{A B}, A B$, and $\triangle A B C$ are constructible figures if $A, B, C$ are constructible points. Also the union of constructible figures can be said to be constructible as well.

Definition A positive real number $r$ is constructible if there exist constructible points $P, Q$ with $|P Q|=r$.

## Constructions with Geometer's Sketchpad

Here are a few useful and important tips to keep in mind when using Geometer's Sketchpad.

- The four rules of construction in the definition of contructible can be accomplished in Sketchpad in the following way:

1. To construct arbitrary given points such as $O, A$ use the Point tool (the button with the dot on it on the left hand side of the screen) and just click anywhere to make the point.
2. To construct a line (or a segment or ray) through two points $X, Y$ select the Line Tool (the button with the segment on it on the left hand side of the screen). If you click on that button and hold down the mouse button another row of buttons pops out and you can select between segment, ray, or line. Then move the cursor over point $X$ until it turns blue and click the left mouse button, then move the cursor over point $Y$ until it turns blue and then click the left button again.
3. To construct a circle with a given center $X$ and containing point $Y$ select the Circle Tool from the left hand side of the screen. Then click first on $X$ and then on $Y$.
4. To construct the point of intersection of two figures (lines or circles), select the Point tool, and move the cursor over the point of intersection until both circles/lines turn blue. Then click the left mouse button.

- The Text tool (the button with the A on it) can be used to type text and mathematics into your document. Double click on the document to open up a text box. You can resize the text boxes with the Selection tool by dragging the lower right hand corner of the box. You can select the entire box and reposition it on the screen with the Selection tool also (just click on the box and then drag it whereever you like). You can insert math symbols into your text using the toolbar that appears at the bottom of the screen.
- To select lines, segments, rays, circles, arcs, or points, use the Selection tool (the button with the arrow on it) on the left hand side of the screen. You can select items by clicking on them or by dragging a box around them with the mouse to select everything inside the box (press and hold the left mouse button while dragging).
- Selected objects can be hidden by pressing CTRL-H. This is very useful for un-cluttering
your drawing and making scripts. To unhide objects choose Display/Show All Hidden from the menu.
- If you select two or more points (and NOTHING else!!) and press CTRL-L, it will construct line segments between all of the points.
- If you select a segment and press CTRL-M it will construct the midpoint of the segment.
- If your mouse has a middle wheel button, you can use it to change between the various buttons on the left hand side of the screen. This is very efficient compared with clicking on the buttons themselves. Clicking the middle mouse wheel changes the selection for the line button between segment, ray, and line.
- If you right click on an object you can change it's color, make lines or circles dashed, solid, or thick, and label the object.
- If you label a point, the label remains attached to the point, but you can drag it to a more convenient position with the selection tool by moving it over the label until it changes from an arrow to a hand and then clicking and dragging the label.
- Most menu items, such as those on the Construct menu, require that very specific inputs be selected in your diagram before the menu item can be used. So if you have a menu item and it is greyed-out (not available) it is because you have not selected the correct inputs for it to be available. For example, if you want to construct a Circle-by-Center-and-Radius you must select one point and one line segment. A common mistake I make over and over again is to have something ELSE selected and not notice it, for example, if I have selected a point, a segment, and a text box. So if your menu item is not available the reason is simple: you have to select the correct inputs for that menu item, nothing more, and nothing less.
- To create a script construct a figure by hand. Then select (a) the points you want as inputs to the script and (b) the objects you want the script to construct from your given points. Then click and hold on the Tool button on the left hand side of the screen (the one with the double black triangles) and choose Create New Tool... . You do not need to highlight everything you have used to do the construction, only your starting points and your ending points. Note that the order that you click on the input points while highlighting will match the order that those points will be matched when you execute the script.
- To show the script itself (i.e. to read the description of your construction), you can turn on the Script View from the Tool button.


## Basic Constructions

Remark Every constructible line contains at least two constrictible points. The center of every constructible circle is constructible and every constructible circle contains at least one constructible point. This follows immediately from the definition of constructible, since no line or circle can be constructed without such points.

Theorem (perpendiculars are constructible) If lis a constructible line and P a constructible point then the line perpendicular to l through $P$ is constructible.

Theorem (parallels are constructible) Ifl is a constructible line and Pa constructible point
then the line parallel to l through $P$ is constructible.

Theorem (noncollapsible compass) If $A, B, P$ are distinct constructible points and $A \neq B$ then the circle centered at $P$ with radius $|A B|$ is constructible.

Corollary (copy segments) Given a contructible segment and constructible ray $\overrightarrow{A B}$, we can construct a point $C$ on $\overrightarrow{A B}$ so that $A C$ is congruent to the given segment.

Remark Thus we can copy any constructible segment onto any constructible ray.

Theorem (copy triangles) If $\triangle A B C$ is constructible and $\overrightarrow{D E}$ are constructible then we can construct $P$ on $\overrightarrow{D E}$ and $Q$ such that $\triangle A B C \equiv \triangle D P Q$.

Corollary (copy angles) Given a contructible angle and constructible ray $\overrightarrow{A B}$, we can construct a ray $\overrightarrow{A C}$ so that $\angle A$ is congruent to the given angle.

Theorem (midpoints) If $A B$ is constructible then the midpoint of $A B$ is constructible.

Theorem (angle bisectors) If $\angle A$ is constructible then so is its angle bisector.

## Geometric Mean

Definition The geometric mean of two positive real numbers $a, b$ is $\sqrt{a b}$.

Theorem In any right triangle $\triangle A B C$ with right angle at $A$, the length of the altitude $A P$ is the geometric mean of the lengths of the segments $B P$ and $C P$, i.e.

$$
|A P|^{2}=|B P||C P|
$$



## Doing Arithmetic with Geometry

Theorem If $x, y$ are constructible real numbers then
(1) $x+y$ is constructible.
(2) $|x-y|$ is constructible.
(3) $x / y$ is constructible.
(4) $x y$ is constructible.
(5) $\sqrt{x}$ is constructible.

Corollary The positive rational numbers are constructible.

## Non-Euclidean Geometry

A First look at Hyperbolic Geometry

Definition Neutral Geometry is the collection of theorems that can be proven using all of the axioms of Euclidean geometry except the parallel axiom, i.e. any theorem that can be proven using only axioms S1-S11 is a theorem of neutral geometry.

Definition Hyperbolic Geometry consists of all theorems that can be proven from the axiom system for Euclidean geometry with the parallel axiom replaced by its negation, i.e. any theorem that can be proven from axioms S1-S11 and $\sim S 12$.

Remark Every theorem of Neutral Geometry is thus a theorem of both Euclidean Geometry and Hyperbolic Geometry.

Definition A Hyperbolic plane, H, is an incidence structure $(\mathcal{P}, \mathcal{L})$ satisfying S1-S11 and the negation of S12.

Remark Technically speaking, when we refer to the Euclidean plane and the Hyperbolic plane as incidence structures satisfying certain axioms, we are actually talking about models for these axiom systems.

## A Toy Euclidean Plane

There are many bijections from the Euclidean plane to the open unit disk. Here are two.
Theorem * Label the points in the plane uniquely in polar coordinates $(r, \theta)$ by requiring that $r>0$ and $0 \leq \theta<360$ for points not on the origin and label the origin $(0,0)$. Then the function

$$
f(r, \theta)=\left(1-\frac{1}{2^{r}}, \theta\right)
$$

is a bijective function from the entire plane to the interior of the unit circle.

Theorem * Label the points in the plane as in the previous theorem. Then the function

$$
f(r, \theta)=\left(\frac{r}{\sqrt{1+r^{2}}}, \theta\right)
$$

is a bijective function from the entire plane to the interior of the unit circle.

## Statements Equivalent to the Euclidean Parallel Axiom

Theorem In neutral geometry, the following statements are equivalent.

1. Through any point not on a line there is exact one line parallel to the given line.
2. If two lines and a transveral form same side interior angles whose sum is less than 180 then the lines intersect on the same side of the transversal as those two angles.
3. If $l, m, n$ are three distinct lines with $l \| m$ and $m \| n$ then $l \| n$.
4. A line that intersects one of two parallel lines must also intersect the other.
5. A line perpendicular to one of two parallel lines is perpendicular to the other.
6. The perpendicular bisectors of the sides of a triangle are concurrent.
7. Any triangle can be circumscribed by a circle.
8. A line perpendicular to one ray of an acute angle intersects the other ray.
9. Through any point in the interior of an angle there exists a line intersecting both rays of the angle at points other than the vertex.
10. There exists an acute angle such that every point in the interior is on a line that intersects both rays.
11. The sum of the measures of the angles of any triangle is 180.
12. There exists a triangle whose angle sum is 180.
13. The perpendicular bisectors of the legs of a right triangle intersect.
14. There exists a pair of similar, noncongruent triangles.
15. Rectangles exist.

## Some theorems of Hyperbolic Geometry

Theorem In hyperbolic geometry:

1. Rectangles do not exist.
2. $A A A$
3. The angle sum of every triangle is less than 180.
4. Through any point not on a line there are infinitely many lines which are parallel to the given line.
5. There exist four lines $l, m, n, r$ such that $l \perp m, m \perp n, n \perp r$, and $l \| r$.
6. The interior of any angle contains two perpendicular lines.

## A Toy Hyperbolic Pane

Definition The Poincare Disk is an incidence structure ( $\mathcal{P}, \mathcal{L})$ where $\mathcal{P}$ is the set of points in the interior of the unit circle in the complex plane, and $\mathcal{L}$ consists of the intersections of $\mathcal{P}$ with lines or circles in the complex plane that are perpendicular to the unit circle at both points of intersection. The hyperbolic distance between points $z, w$ is

$$
d(z, w)=\operatorname{arctanh}\left(\frac{z-w}{1-\bar{z} w}\right)
$$

The hyperbolic measure of hyperbolic angles is the same as the Euclidean angle measure of the hyperbolic rays (where we use the Euclidean angle between the Euclidean tangents when the hyperbolic rays are arcs of Euclidean circles).

Theorem The Poincare disk is a model of hyperbolic geometry.

## Analytic Geometry: the Complex Plane

Definition Let $\mathbb{C}=\mathbb{R}^{2}$. For each $(x, y) \in \mathbb{C}$ we formally write $(x, y)=x+y$ i. This form, $x+y i$, is called the standard form of the complex number $(x, y)$.

Definition Let $x+y i, a+b i \in \mathbb{C}$, then:

1. $\overline{x+y i}=x-y i$. (This is called the complex conjugate.)
2. $|x+y i|=\sqrt{x^{2}+y^{2}}$. (This is called the complex norm.)
3. $\operatorname{Arg}(x+y i)=$ the angle in $[0 \ldots 2 \pi)$ of $(x, y)$ in polar form (not defined for $x=y=0$ ).
(This is called the Argument of $x+y i$.)
4. $\operatorname{Re}(x+y i)=x$. (This is called the real part of $x+y i$.)
5. $\operatorname{Im}(x+y i)=y$. (This is called the imaginary part of $x+y i$.)
6. $(x+y i)+(a+b i)=(x+a)+(y+b)$ i. (This is the definition of addition in $\mathbb{C}$.)
7. $(x+y i)(a+b i)=(x a-y b)+(y a+x b) i$. (This is the definition of multiplication in $\mathbb{C}$.)

Notation We can abbreviate $0+y i$ as $y i, x+0 i$ as $x, x+1 i$ as $x+i$, and $x-1 i$ as $x-i$ with no ambiguity in the above definitions. With this notation $i=(0,1)$ and $i^{2}=-1$. It is easy to verify that the usual laws of addition and multiplication (associative, commutative, distributive, identity, etc.) hold for the complex numbers as well.
Definition Let $\theta \in \mathbb{R}$. Then $e^{i \theta}=\cos \theta+i \sin \theta$
Definition Let $x+y i \in \mathbb{C}-\{0\}$. The standard polar form of $x+y i$ is re ${ }^{i \theta}$ where $r=|x+y i|$ and $\theta=\operatorname{Arg}(x+y i)$.
Definition The distance between two complex numbers $z, w$ is denoted $d(z, w)$ and is defined to be $d(z, w)=|z-w|$.

Theorem $e^{i \pi}+1=0$ (The most beautiful theorem in mathematics?)
Theorem Let $\theta, \gamma \in \mathbb{R}$

1. $e^{i \theta} e^{i \gamma}=e^{i(\theta+\gamma)}$.
2. $\left|e^{i \theta}\right|=1$.
3. $\overline{e^{i \theta}}=e^{i(-\theta)}$.

Theorem Let $z, z_{1}, z_{2} \in \mathbb{C}$. Then:

1. $\left|z_{1} z_{2}\right|=\left|z_{1}\right|\left|z_{2}\right|$
2. $\overline{z_{1} z_{2}}=\overline{z_{1}} \overline{z_{2}}$ i.e. the conjugate of a product is the product of conjugates.
3. $\overline{z_{1}+z_{2}}=\overline{z_{1}}+\overline{z_{2}}$ i.e. the conjugate of a sum is the sum of the conjugates.
4. $z \bar{z}=|z|^{2}$
5. $|z|=|\bar{z}|$
6. If $z=r e^{i \theta}$ in polar form, then $\bar{z}=r e^{i(-\theta)}$

## Transformations

Definition A transformation of a set $S$ is a bijection from $S$ to $S$.

Remark In other branches of mathematics a transformation of $S$ is often called a permutation of $S$.

Some Useful Geometric Transformations Let $w \in \mathbb{C}$ and $\theta, k \in \mathbb{R}$.
Translation by $w: T(z)=z+w$
Rotation by $\theta$ radians counterclockwise about the origin: $T(z)=e^{i \theta} z$
Reflection across the $x$-axis: $T(z)=\bar{z}$
Homothety by positive factor $k$ with respect to the origin: $T(z)=k z$
Inversion* with respect to the unit circle: $T(z)=\frac{1}{\bar{z}}$
*Inversion is a transformation of the extended complex plane $\mathbb{C}^{+}=\mathbb{C} \cup\{\infty\}$ with $\frac{1}{0}=\infty$ and $\frac{1}{\infty}=0$.

Remark You can compose these functions to obtain many useful transformations!

## Inversion

Remark Henle defines inversion in the unit circle by $T(z)=\frac{1}{z}$. We will call this algebraic inversion as opposed to the inversion $T(z)=\frac{1}{\bar{z}}$ which we will call geometric inversion. The term inversion will refer to geometric inversion in these lecture notes.

Theorem Geometric inversion in the unit circle sends re ${ }^{i \theta}$ to $\frac{1}{r} e^{i \theta}$ for $r \neq 0$ and it sends 0 and $\infty$ to each other.

Definition Given a circle $\odot O A$ with radius $R$, if $P$ is a point other than $O$ we define the geometric inverse of $P$ with respect to $\odot O A$ to be the point $P^{\prime}$ on $\overrightarrow{O P}$ such that $\left|O P \| O P^{\prime}\right|=R^{2}$. The inverse of $O$ is $\infty$ and vice versa.

Theorem * If P is outside of $\odot O A$ and $Q$ and $R$ are the points where the tangent lines through $P$ meet $\odot O A$, then the inverse of $P$ is the midpoint of $Q R$. Similarly if $P$ is inside
$\odot O A$ and $Q$ and $R$ are the points where the perpendicular to $O P$ through $P$ meets $\odot O A$, then the tangent lines to $\odot O A$ at $Q$ and $R$ intersect at the inverse $P^{\prime}$ of $P$ with respect $\odot O A$.

Definition A cline is either a circle or a line.

Theorem Geometric inversion with respect to a circle maps clines to clines.
In particular,

1. Points on the circle of inversion map to themselves
2. The center of the circle of inversion maps to infinity and vice versa.
3. Points inside the circle of inversion map to points outside the circle of inversion and vice versa.
4. The only clines which map to themselves are those that are orthogonal to the circle of inversion at both points of intersection, and the circle of inversion itself.

## Geometry

## Groups

Definition A group is a pair $(G, *)$ where $G$ is a set and $*: G \times G \rightarrow G$ is a binary operation such that:

1. $*$ is associative (i.e. $\forall a, b, c \in G,(a * b) * c=a *(b * c))$
2. There is an identity element for $*$ in $G$ (i.e. $\exists e \in G, \forall a \in G, a * e=a$ and $e * a=a$ )
3. Every element has an inverse (i.e. $\forall a \in G, \exists a^{-1} \in G, a * a^{-1}=e$ and $a^{-1} * a=e$ )

Theorem For any nonempty set $G$ of transformations of a set $S$, if

1. $G$ is closed under composition (i.e. $\forall g, h \in G, g \circ h \in G$ )
2. $G$ is closed under taking inverses (i.e. $\forall g \in G, g^{-1} \in G$ )
then ( $G, \circ$ ) is a group.

Corollary The set of all transformations of a set S forms a group with composition as the operator.

Definition The group in the previous corollary is called the symmetric group on $S$ and is denoted $\operatorname{Sym}(S)$.

Remark It is commonplace to refer to the group $(G, *)$ by the set $G$ and vice versa, when the operation $*$ is understood. For geometry we will only be concerned with the case where $G$ is a set of transformations and $*$ is composition.

Definition If $G, H$ are groups of transformations and $G \subseteq H$ we say $G$ is a subgroup of $H$.

Remark This does not imply that every subset of a group is a subgroup. The subset must be
closed under composition and inverses for it to be a subgroup.

Corollary Every group of transformations is a subgroup of a symmetric group.

From now on we will only talk about transformation groups, i.e. subgroups of a symmetric group, i.e. groups of transformations of a set $S$ with composition as the operation.

## Klein's Erlanger Program

Felix Klein - your greatgreatgreatgreatgreatgreatgrandpop!
(see: http://math.scranton.edu/monks/misc/Lineage.html)

Definition A geometry is pair $(S, G)$ where $S$ is a set and $G$ is a group of transformations of S. The set $S$ is called the underlying space of the geometry and $G$ is called the group of transformation or the transformation group of the geometry.

Definition The elements of the underlying set of a geometry are called points. A figure is a set of points in a geometry.

Definition Two figures are congruent in a geometry if and only if there is a transformation in that geometry that maps one to the other, i.e. if $(S, G)$ is a geometry and $U, V \subseteq S$, then

$$
U \equiv V \Leftrightarrow \exists T \in G, T(U)=V
$$

Theorem * Congruence is an equivalence relation on the set of all figures in a geometry.

## Invariants

Definition $A$ set of figures $\mathcal{F}$ in a geometry $(S, G)$ is said to be invariant if and only if the image of any figure in $\mathcal{F}$ under any transformation in $G$ is also an element of $\mathcal{F}$, i.e. $\mathcal{F}$ is invariant if and only if

$$
\forall U \in \mathcal{F}, \forall T \in G, T(U) \in \mathcal{F}
$$

Remark Thus a set of figures is invariant if whenever a figure is in the set, so is every figure that is congruent to it.

Definition More generally, if $\mathcal{F}_{1}, \mathcal{F}_{2}, \mathcal{F}_{3}, \ldots, \mathcal{F}_{n}$ are sets of figures in a geometry $(S, G)$ and $\mathcal{F}$ is a subset of $\mathcal{F}_{1} \times \mathcal{F}_{2} \times \cdots \times \mathcal{F}_{n}$ then $\mathcal{F}$ is said to be an invariant set of $n$-tuples if and only for any transformation in $G$ and any tuple $\left(A_{1}, A_{2}, \ldots, A_{n}\right)$ in $\mathcal{F}$, the tuple $\left(T\left(A_{1}\right), T\left(A_{2}\right), \ldots, T\left(A_{n}\right)\right)$ is also an element of $\mathcal{F}$, i.e. $\mathcal{F}$ is invariant if and only if

$$
\forall\left(A_{1}, A_{2}, \ldots, A_{n}\right) \in \mathcal{F}, \forall T \in G,\left(T\left(A_{1}\right), T\left(A_{2}\right), \ldots, T\left(A_{n}\right)\right) \in \mathcal{F}
$$

Definition A function $f$ whose domain is an invariant set of figures $\mathcal{F}$ in a geometry is invariant if and only if the value of $f$ on a figure is the same as the value of fon the image of a figure under any transformation, i.e. f is invariant in geometry $(S, G)$ if and only if

$$
\forall U \in \mathcal{F}, \forall T \in G, f(U)=f(T(U))
$$

Remark Thus a function on a set of figures is invariant if whenever figure $U$ is congruent to figure $V, f(U)=f(V)$.

Definition More generally for multivariable functions, let $(S, G)$ be a geometry and $\mathcal{F}$ be an invariant set of n-tuples figures in $(S, G)$. A function $f: \mathcal{F} \rightarrow C$ where $C$ is any set is invariant if and only if for every $T$ in $G$, and every $\left(A_{1}, A_{2}, \ldots, A_{n}\right) \in \mathcal{F}$

$$
f\left(A_{1}, A_{2}, \ldots, A_{n}\right)=f\left(T\left(A_{1}\right), T\left(A_{2}\right), \ldots, T\left(A_{n}\right)\right)
$$

The Study of a Particular Geometry: is the study of its invariant sets and functions!

## Examples of Geometries

Euclidean geometry: $\left(\mathbb{C}, \mathbf{E}^{+}\right)$where $\mathbf{E}^{+}$is the set of all transformations of $\mathbb{C}$ of the form

$$
T(z)=e^{i \theta} z+\gamma \text { or } T(z)=e^{i \theta} \bar{z}+\gamma
$$

where $\theta \in \mathbb{R}$ and $\gamma \in \mathbb{C}$.
Definition An isometry is a distance preserving transformation, i.e. Tis an isometry if and only if for all $z, w, d(z, w)=d(T(z), T(w))$.

Theorem (Classification) The transformation group for Euclidean geometry consists of the set of all reflections, rotations, translations, and glide reflections (a translation followed by reflection in a line parallel to the direction of translation).

Theorem * A transformation $T$ of $\mathbb{C}$ is an isometry if and only if there exists $\theta \in \mathbb{R}$ and $\gamma \in \mathbb{C}$ such that

$$
T(z)=e^{i \theta} z+\gamma \text { or } T(z)=e^{i \theta} \bar{z}+\gamma
$$

Special Euclidean Geometry: (Henle's Euclidean geometry) ( $\mathbb{C}, \mathbf{E}$ ) where $\mathbf{E}$ is the set of all rigid motions, i.e. all transformations of $\mathbb{C}$ of the form

$$
T(z)=e^{i \theta} z+\gamma
$$

where $\theta \in \mathbb{R}$ and $\gamma \in \mathbb{C}$.

Theorem * Every transformation of $\mathbb{C}$ obtained by composing one or more translations and

## rotations is a rigid motion and vice versa.

Translational Euclidean Geometry: (Henle calls this translational geometry) ( $\mathbb{C}, \mathcal{T}$ ) where $\mathcal{T}$ is the set of all translations, i.e. all transformations of $\mathbb{C}$ of the form

$$
T(z)=z+\gamma
$$

where $\gamma \in \mathbb{C}$.
Rotational Euclidean Geometry: (Henle calls this rotational geometry) $(\mathbb{C}, \mathcal{R})$ where $\mathcal{R}$ is the set of all rotations about the origin, i.e. all transformations of $\mathbb{C}$ of the form

$$
T(z)=e^{i \theta} z
$$

where $\theta \in \mathbb{R}$.
Trivial Geometry: $\left(\mathbb{C},\left\{i d_{\mathbb{C}}\right\}\right)$
Note: A group with one element is called a trivial group.
Extreme Geometry: $(S, \operatorname{Sym}(S))$ where $S$ is any set.

Hyperbolic Geometry: (D, H) where D is the open unit disk

$$
\mathbf{D}=\{z \in \mathbb{C}:|z|<1\}
$$

and $\mathbf{H}$ is the set of transformations of $\mathbf{D}$ of the form

$$
T(z)=e^{i \theta} \frac{z-\gamma}{1-\bar{\gamma} z}
$$

where $\gamma \in \mathbb{C}$ with $|\gamma|<1$ and $\theta \in \mathbb{R}$.
[Note: this is actually Special Hyperbolic Geometry, i.e. hyperbolic geometry without reflections.]

Elliptic Geometry: $\left(\mathbb{C}^{+}, S\right)$ where $S$ is the set of transformations of $\mathbb{C}^{+}$of the form

$$
T(z)=e^{i \theta} \frac{z-\gamma}{1+\bar{\gamma} z}
$$

where $\gamma \in \mathbb{C}$ with $|\gamma|<1$ and $\theta \in \mathbb{R}$.
Möbius Geometry: $\left(\mathbb{C}^{+}, \mathbf{M}\right)$ where $\mathbf{M}$ is the set of transformations of $\mathbb{C}^{+}$of the form

$$
T(z)=\frac{a z+b}{c z+d}
$$

where $a, b, c, d \in \mathbb{C}$ and $a d-b c \neq 0$.
Affine Geometry: $(\mathbb{C}, L)$ where $L$ is the set of transformations of $\mathbb{C}$ of the form

$$
T(z)=\alpha z+\beta \bar{z}+\gamma
$$

where $\alpha, \beta, \gamma \in \mathbb{C}$ and $|\alpha| \neq|\beta|$.

Projective Geometry: $\left(\mathbb{P}^{2}, \mathbb{P}\right)$ where $\mathbf{P}$ is the set of projective transformations (defined later) of the real projective plane $\mathbb{P}^{2}$.

## Complex Analytic Geometry

Direction Number

Definition Let z be a nonzero complex number. The direction number of $z$ is the complex number

$$
\operatorname{dir}(z)=\frac{z}{\bar{z}}
$$

Theorem Let $z \in \mathbb{C}-\{0\}$ and $\theta=\operatorname{Arg}(z)$. Then

$$
\operatorname{dir}(z)=e^{2 \theta i}
$$

## Complex Equation of a Euclidean Line

Definition $A$ T transformation in $\mathbf{E}^{+}$is a reflection if $T(z)=e^{i \theta} \bar{z}+\gamma$ and $T$ has fixed points.

Remark The transformations $T(z)=e^{i \theta} \bar{z}+\gamma$ that do not have fixed points are the glide reflections.

Definition $A$ line in Euclidean geometry $\left(\mathbb{C}, \mathbf{E}^{+}\right)$is the set of fixed points of a reflection.

Remark Note that while we can develop Euclidean geometry this way, Henle assumes we already know what a Euclidean line is in $\mathbb{C}$ without having to prove everything from this definition.

Theorem For any two distinct points there is exactly one line which contains them both.

Remark Thus axiom S1 in the SMSG axiomatic development of Euclidean Geometry is a theorem in the Erlanger Program development of Euclidean Geometry. Similiarly, by making appropriate definitions, we can prove the rest of the SMSG axioms as theorems in the Erlanger Program view..

Theorem Let v,w be distinct complex numbers. The solution set of

$$
\operatorname{dir}(z-w)=\operatorname{dir}(v-w)
$$

is the Euclidean line through the points $v, w$.

[^0]to be
$$
\operatorname{dir}(l)=\operatorname{dir}(v-w)
$$
where $v, w$ are any two distinct points on $l$.

Theorem * The direction number of a line does not depend on which points $v, w$ on the line are used.

## Direction Number of a Angle

Definition Let $P, Q, R$ be distinct complex numbers and $\theta=|\angle P Q R|$. The the direction number of the angle $\angle P Q R$ is

$$
\operatorname{dir}(\angle P Q R)=e^{2 \theta i}
$$

Theorem Let $P, Q, R$ be distinct points. Then

$$
\operatorname{dir}(\angle P Q R)=\frac{\operatorname{dir}(\overleftrightarrow{Q P})}{\operatorname{dir}(\overleftrightarrow{Q R})} \text { or } \operatorname{dir}(\angle P Q R)=\frac{\operatorname{dir}(\overleftrightarrow{Q R})}{\operatorname{dir}(\overleftrightarrow{Q P})}
$$

Remark $\angle P Q R$ is acute if and only if $\operatorname{dir}(\angle P Q R)$ is equal to whichever of $\frac{\operatorname{dir}(\overleftrightarrow{Q P})}{\operatorname{dir}(\overleftrightarrow{Q R})}$ and $\frac{\operatorname{dir}(\overleftrightarrow{Q R})}{\operatorname{dir}(\overleftrightarrow{Q P})}$ has positive imaginary part.

Theorem Two Euclidean angles are congruent if and only their direction numbers are the same.

## The Universal Proving Machine!

To prove a theorem in a geometry which only deals with functions and figures which are invariant for that geometry, it suffices to prove it for one well-chosen example in each congruence class, since by definition of invariance, if the theorem is verified for one example it must be true for all situations that are congruent to that example.

Example Prove that the medians of a triangle are concurrent at a point $2 / 3$ of the way from each vertex to the midpoint of the opposite side by the Erlanger Program method.

## Möbius Geometry

Conformal Maps

## Definition If c, d are smooth curves in the Euclidean plane that intersect at a point $P$, then

the angle between the curves at point $P$ is defined to be the angle between their respective tangent lines at $P$.

Definition $A$ continuous transformation of the Euclidean plane is conformal at a point $P$ if it preserves angles at $P$, i.e. if T is a conformal map and smooth curves $c, d$ meet at a point $P$ at an angle $\theta$ then the angle between $T(c)$ and $T(d)$ at $T(P)$ is also $\theta$. A transformation is conformal if it is conformal at every point in its domain.

Definition In Möbius geometry and its subgeometries, the angle between two curves is defined to be the same as it is in Euclidean geometry.

Remark Clearly translation, rotation, reflection, and glide reflection are all conformal.

Theorem Algebraic inversion is conformal at every point except the origin.

Corollary Geometric inversion is conformal at every point except the center of inversion.

## Möbius Transformations

Definition A Möbius Transformation is a transformation of the extended complex plane $\mathbb{C}^{+}$ of the form

$$
T(z)=\frac{a z+b}{c z+d}
$$

where $a, b, c, d \in \mathbb{C}$ and $a d-b c \neq 0$.

Remark Möbius transformations include all translations, rotations, homotheties, and algebraic inversions in circles.

Remark If $c \neq 0$ then

$$
\frac{a z+b}{c z+d}=\frac{a}{c}-\frac{a d-b c}{c^{2}}\left(\frac{1}{z+\frac{d}{c}}\right)
$$

and so these Möbius transformations are a composition of a translation, inversion, homothety and rotation, and another translation.

If $c=0$ then

$$
\frac{a z+b}{c z+d}=\frac{a}{d} z+\frac{b}{d}
$$

and so these Möbius transformations are a composition of a translation followed by a homothety and rotation.

Thus every Möbius transformation is a composition of rotations, translations, homotheties, and algebraic inversions.

## Matrix of a Möbius Transformation

Lemma If $T(z)=\frac{a z+b}{c z+d}$ and $S(z)=\frac{e z+f}{g z+h}$ are Möbius transformations then

$$
T \circ S(z)=\frac{(a e+b g) z+(a f+b h)}{(c e+d g) z+(c f+d h)}
$$

Definition If $T(z)=\frac{a z+b}{c z+d}$ is a Möbius transformation then the matrix

$$
\left(\begin{array}{ll}
a & b \\
c & d
\end{array}\right)
$$

is called the matrix associated with the Möbius transformation $T$.

Corollary The matrix associated with $T \circ S$ is the matrix product of the matrix associated with $T$ and the matrix associated with $S$.

Lemma If $T(z)=\frac{a z+b}{c z+d}$ is a Möbius transformation then $T^{-1}(z)=\frac{d z-b}{-c z+a}$ and $T^{-1}$ is also a Möbius transformation.

Corollary Möbius geometry is a geometry.

## Fixed Points

Theorem A Möbius transformation other than the identity has either one or two fixed points.

Corollary The only Möbius transformation that has three or more fixed points is the identity map.

## Fundamental Theorem

## Theorem (Fundamental Theorem of Möbius Geometry) Given six points

$z_{1}, z_{2}, z_{3}, w_{1}, w_{2}, w_{3} \in \mathbb{C}^{+}$with $z_{1}, z_{2}, z_{3}$ distinct and $w_{1}, w_{2}, w_{3}$ distinct there is a unique Möbius transformation T mapping $z_{1}$ to $w_{1}, z_{2}$ to $w_{2}$, and $z_{3}$ to $w_{3}$.

## Cross Ratio

## Definition The cross ratio of $z_{1}, z_{2}, z_{3}, z_{4} \in \mathbb{C}^{+}$is

$$
\left\langle z_{1}, z_{2}, z_{3}, z_{4}\right\rangle=\frac{z_{1}-z_{3}}{z_{1}-z_{4}} \frac{z_{2}-z_{4}}{z_{2}-z_{3}}
$$

Remark If $z_{2}, z_{3}, z_{4}$ are distinct then the function

$$
T(z)=\left\langle z, z_{2}, z_{3}, z_{4}\right\rangle
$$

is the unique Möbius transformation sending $z_{2}$ to $1, z_{3}$ to 0 , and $z_{4}$ to $\infty$.

Theorem The cross ratio of four distinct points is an invariant of Möbius geometry.

Corollary The cross ratio of four distinct points is an invariant of special Euclidean, Hyperbolic, and Elliptic geometry.

Theorem Let $a, b, c$ be distinct points. The cross ratio $\langle z, a, b, c\rangle$ is real if and only if $z$ is on the Euclidean circle or line containing $a, b, c$.

Corollary The set of clines is an invariant of Möbius geometry.

## Corollary In Möbius geometry all clines are congruent.

## Symmetry

Definition Two points $z^{*}$ and $z$ in the extended complex plane are symmetric with respect to the cline containing the distinct points $z_{2}, z_{3}, z_{4}$ if and only if

$$
\left\langle z^{*}, z_{2}, z_{3}, z_{4}\right\rangle=\overline{\left\langle z, z_{2}, z_{3}, z_{4}\right\rangle}
$$

Theorem If $z_{2}, z_{3}, z_{4}$ are distinct and collinear then the map that sends $z$ to $z^{*}$ is reflection in the line containing the three points. If $z_{2}, z_{3}, z_{4}$ are distinct and not collinear then the map that sends $z$ to $z^{*}$ is geometric inversion in the circle containing the three points.

Theorem Symmetry is an invariant of Möbius geometry.

## Hyperbolic Geometry

Definition Hyperbolic geometry is ( $\mathbf{D}, \mathbf{H}$ ) where $\mathbf{D}$ is the open unit disk

$$
\mathbf{D}=\{z \in \mathbb{C}:|z|<1\}
$$

and $\mathbf{H}$ is the set of transformations of $\mathbf{D}$ of the form

$$
T(z)=e^{i \theta} \frac{z-\gamma}{1-\bar{\gamma} z}
$$

```
where }\gamma\in\mathbb{C}\mathrm{ with }|\gamma|<1\mathrm{ and }0\in\mathbb{R}\mathrm{ .
```

Theorem H is the group of all Möbius transformations that map the open unit disk to itself.

Definition A hyperbolic straight line is the intersection with the open unit disk of a Euclidean circle or line in the complex plane that meets the unit circle at two right angles.

## Definition The points on the Euclidean unit circle (which are not points in hyperbolic

 geometry) are called ideal points.Remark Henle says that two hyperbolic lines are parallel if the Euclidean clines that contain them intersect at an ideal point. He calls two hyperbolic lines that do not intersect either at a hyperbolic or ideal point hyperparallel.

Definition Two distinct clines are orthogonal if they intersect at right angles.

Theorem For any cline $\Gamma$ and distinct points $A, B \in \mathbb{C}^{+}$there exists a unique cline $\Delta$ through $A, B$ which is orthogonal to $\Gamma$. Furthermore, in this situation the geometric inverse of any point on $\Delta$ is also on $\Delta$.

Theorem All hyperbolic straight lines are congruent in hyperbolic geometry.

Theorem In hyperbolic geometry, through any two distinct points there is exactly one hyperbolic straight line.

Theorem The sum of the measures of the angles in any triangle in hyperbolic geometry is less than 180.

## Example Proofs

## Euclidean Geometry

In the following theorems all points, lines, etc are assumed to be in $\mathbb{E}$. Proofs use the SMSG axioms and definitions given in the Euclidean geometry sections of the lecture notes above. Proofs of theorems from the Review of Some Elementary Theorems section above are labled (Thm n.) where $n$ is the theorem number.

```
Lemma (relabeling) If \(A, B, C, D\) are collinear points and \(A \neq B\) and \(C \neq D\) then \(\overleftrightarrow{A B}=\overleftrightarrow{B A}\) and \(\overleftrightarrow{A B}=\overleftrightarrow{C D}\)
```


## Proof:

1. $A, B, C, D$ are collinear
2. $A \neq B$ and $C \neq D$
given
3. $A \in l$ and $B \in l$ and $C \in l$ and $D \in l$ for some line $l$
4. $\overleftrightarrow{A B}$ is the unique line containing $A, B$
5. $l=\overleftrightarrow{A B}$
6. $\overleftrightarrow{B A}$ is the unique line containing $B, A$
7. $l=\overleftrightarrow{B A}$
8. $\overleftrightarrow{C D}$ is the unique line containing $C, D$
9. $l=\overleftrightarrow{C D}$ def collinear; 1
2 pts det a line (Axiom S1);2
def unique; $4 ; 3$
2 pts det a line (Axiom S1);2
def unique; $6 ; 3$
2 pts det a line (Axiom S1);2
def unique; $8 ; 3$
10. $\overleftrightarrow{A B}=\overleftrightarrow{B A}$ and $\overleftrightarrow{A B}=\overleftrightarrow{C D}$
substitution;5,7,9
QED

Remark Because of this Lemma, we won't fuss over relabeling lines in our proofs, and will treat all such relabelings as equivalent names for the same line. A similar comment will apply when we prove other relabeling lemmas in the future.
Theorem (Thm 5.)If A.B.C then C.B.A.

## Proof:

1. $A . B . C$

Given
2. $A, B, C$ are distinct collinear point
3. $|A C|=|A B|+|B C|$
4. $|A C|=|C A|$ and $|A B|=|B A|$ and $|B C|=|C B|$
5. $|C A|=|B A|+|C B|$
6. $\quad=|C B|+|B A|$
7. C.B.A

QED

Lemma (relabeling) If $A, B$ are distinct points then $A B=B A$.

## Proof:

1. $A, B$ are distinct points

Given
2. $A B=\{C: C=A$ or $C=B$ or $A \cdot C \cdot B\}$
3. $=\{C: C=B$ or $C=A$ or $B \cdot C \cdot A\}$ def segment
4. $=B A$
def segment
QED

Lemma (distinct pts, distinct coords) If A, $B$ are distinct points and $\Psi$ is a coordinate system for the line containing them, then $\Psi(A) \neq \Psi(B)$.

## Proof:

1. $A, B$ are distinct points

Given
2. $\Psi=\Psi_{\overleftrightarrow{A B}}$
3. $A \neq B$

Given
4. $\Psi$ is bijective def distinct; 1
5. $\Psi$ is injective coordinate axiom (S3) def bijective
6. Assume $\Psi(A)=\Psi(B)$
7. $A=B$
def injective;5;6
8. $\rightarrow \leftarrow$
$\rightarrow \leftarrow+; 7,3$
9. $\leftarrow$
10. $\Psi(A) \neq \Psi(B)$

QED

## Theorem (order thm) Let $A, B, C$ be three distinct collinear points and $\Psi$ a coordinate

 system for the line containing them. Then$$
\Psi(A)<\Psi(B)<\Psi(C) \text { or } \Psi(C)<\Psi(B)<\Psi(A) \Leftrightarrow A . B . C
$$

## Proof:

1. $A, B, C$ are distinct collinear points

Given
2. $\Psi$ a coordinate system for $\overleftrightarrow{A B}$

Given
$(\Rightarrow)$
3. Assume $\Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A)$ (case 1)
4. Assume $\Psi(A)<\Psi(B)<\Psi(C)$
5. $0<\Psi(B)-\Psi(A)$ and $0<\Psi(C)-\Psi(A)$ and $0<\Psi(C)-\Psi(B) \quad$ algebra
6. $|A C|=|\Psi(C)-\Psi(A)| \quad$ coordinate axiom (S3)
7. $=\Psi(C)-\Psi(A) \quad$ def absolute value; 5
8. $=\Psi(C)-\Psi(B)+\Psi(B)-\Psi(A)$
9. $\quad=|\Psi(C)-\Psi(B)|+|\Psi(B)-\Psi(A)|$ algebra
10. $=|\Psi(B)-\Psi(A)|+|\Psi(C)-\Psi(B)|$ def absolute value; 5

$$
=|\Psi(B)-\Psi(A)|+|\Psi(C)-\Psi(B)|
$$

algebra

$$
=|A B|+|B C|
$$

11. $=|A B|+|B C|$
coordinate axiom (S3)
12. A.B. $C$ def between;1,6,11
13. $\leftarrow$
(case 2)
14. Assume $\Psi(C)<\Psi(B)<\Psi(A)$
15. $0<\Psi(B)-\Psi(C)$ and $0<\Psi(A)-\Psi(C)$ and $0<\Psi(A)-\Psi(B) \quad$ algebra
16. $|C A|=|\Psi(A)-\Psi(C)| \quad$ coordinate axiom (S3)
17. $=\Psi(A)-\Psi(C)$
18. $=\Psi(A)-\Psi(B)+\Psi(B)-\Psi(C)$ def absolute value; 15
19. $\quad=|\Psi(A)-\Psi(B)|+|\Psi(B)-\Psi(C)| \quad$ def absolute value; 15
20. 

$$
=|\Psi(B)-\Psi(C)|+|\Psi(A)-\Psi(B)|
$$

algebra
21. $=|B C|+|C A|$
22. C.B.A
23. A.B. $C$
24. $\leftarrow$
25. A.B.C
or-;3,4,12,14,23
26. $\leftarrow$
27. $\Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A) \Rightarrow A . B . C$ $\Rightarrow+; 3,25$
$(\Leftarrow)$
28. Assume A.B.C
29. $\Psi(A), \Psi(B), \Psi(C)$ are distinct dist pts,dist coords lemma;1
30. $\Psi(A)<\Psi(B)<\Psi(C)$ or
$\Psi(C)<\Psi(B)<\Psi(A)$ or
$\Psi(B)<\Psi(A)<\Psi(C)$ or
$\Psi(C)<\Psi(A)<\Psi(B)$ or
$\Psi(A)<\Psi(C)<\Psi(B)$ or
$\Psi(B)<\Psi(C)<\Psi(A) \quad$ trichotomy;29
(case 1 or 2)
31. Assume $\Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A)$
32. $\leftarrow$
(case 3 or 4)
33. Assume $\Psi(B)<\Psi(A)<\Psi(C)$ or $\Psi(C)<\Psi(A)<\Psi(B)$
34. B.A.C
$(\Rightarrow$ ) proof above
35. $|B C|=|B A|+|A C|$ and $|A C|=|A B|+|B C|$
36. $|B C|=|B A|+|A B|+|B C|$
37. $0=2|B A|$
38. $|B A|=0$
39. $|B A|>0$
40. $|B A| \neq 0$
41. $\rightarrow \leftarrow$
42. $\Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A)$
$\rightarrow \leftarrow$ implies anything
43. $\leftarrow$
(case 5 or 6 )
44. (the proof is similar to case 3 or 4 and is omitted here)
45. $\Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A)$ or -; 30,31,31,33,42,44
46. $\leftarrow$
47. $A . B . C \Rightarrow \Psi(A)<\Psi(B)<\Psi(C)$ or $\Psi(C)<\Psi(B)<\Psi(A) \quad \Rightarrow+; 28,45$

QED
Theorem (Thm 10) Midpoints exist and are unique.

## Proof:

1. Let $S$ be a segment
2. $S=A B$ for some distinct points $A, B$
def segment
3. There exists a coordinate system $\Psi$ on $\overleftrightarrow{A B}$ with $\Psi(A)=0$ and $0<\Psi(B) \quad$ ruler placement axiom (S4)
4. $\overleftrightarrow{A B} \xrightarrow{\Psi} \mathbb{R}$ and $\Psi$ is bijective
coordinate axiom (S3)
5. $\Psi$ is surjective def of bijective
6. $\Psi(B) / 2 \in \mathbb{R}$ def of $f(x)$ and closure of real numbers; 4
7. There exists $M \in \overleftrightarrow{A B}$ such that $\Psi(M)=\Psi(B) / 2$ def surjective;5,4
8. $0<\Psi(B) / 2<\Psi(B)$
9. $\Psi(A)<\Psi(M)<\Psi(B)$
10. $A . M . B$
11. $|A M|=|\Psi(M)-\Psi(A)|$
order theorem (Thm 6);9
12. $=|\Psi(B) / 2-0|$
13. $=|\Psi(B) / 2|$
14. $=|\Psi(B)-\Psi(B) / 2|=|\Psi(B)-\Psi(M)|$
15. $=|M B|$
16. $M$ is a midpoint of $S$
17. Every segment has a midpoint
arithmetic
substitution;3,7,8
coordinate axiom (S3)
substitution;3,7,11
arithmetic;2 arithmetic
coordinate axiom (S3)
def midpoint; 10,11,15
( $\star$ Now we show that it's unique $\star$ )
18. Let $N$ be a midpoint of $S$
19. $A . N . B$ and $|A N|=|N B|$
20. $\Psi(A)<\Psi(N)<\Psi(B)$
def of midpoint
21. $0<\Psi(N)$ and $0<\Psi(B)-\Psi(N)$
22. $\Psi(N)=|\Psi(N)-0|$
23. $=|\Psi(N)-\Psi(A)|$
24. $=|A N|$
25. $=|N B|$
26. $\quad=|\Psi(B)-\Psi(N)|$
27. $=\Psi(B)-\Psi(N)$
28. $2 \Psi(N)=\Psi(B)$
29. $\Psi(N)=\Psi(B) / 2$
30. $=\Psi(M)$
31. $\Psi$ is injective
32. $N=M$
33. Midpoints are unique order theorem (Thm 6);3,19 arithmetic and substitution; 3
arithmetic substitution;3
coordinate axiom (S3)
substitution;19
coordinate axiom (S3)
arithmetic;21
algebra;22,27
algebra
substitution;7
def of bijective; 4
def injective;29-31
def of unique; 18,32
QED
Lemma (alternate def of ray) Let $A, B$ be distinct points. Then $X \in \overrightarrow{A B}$ if and only if $X \in \overleftrightarrow{A B}$
```
and ~X.A.B.
```


## Proof:

1. (do in class)

Lemma (sides) If l is a line and points $A, B$ are on the opposite side of l from point $C$ then $A, B$ are on the same side of $l$. Similarly, if $A, B$ are on the same side of $l$ and $C$ is on the opposite side of $l$ as $A$ then $C$ is on the opposite side of $l$ as $B$.

## Proof:

1. $l$ is a line, $A, B, C$ points
given
2. $A$ is on the opposite side of $l$ as $C$
given
3. $B$ is on the opposite side of $l$ as $C$
given
4. $l$ separates the points of the plane not on $l$ into a disjoint union half-planes $L, R$ separation axiom (S6)
5. $C \in R$ or $C \in L$ def union, opposite; $2,3,4$
(case 1:)
6. Assume $C \in R$
7. $A \in L$ and $B \in L$
8. $A, B$ are on the same side of $l$
9. $\leftarrow$
(case 2:)
10. Assume $C \in L$
11. $A \in R$ and $B \in R$
12. $A, B$ are on the same side of $l$
13. $\leftarrow$
14. $A, B$ are on the same side of $l$ or-;5,6,8,10,12

QED

Theorem (Pasch) If l meets side $A C$ in $\triangle A B C$ at exactly one point between $A$ and $C$ then $l$ intersects $A B$ or $B C$.

## Proof:

1. $l$ meets side $A C$ in $\triangle A B C$ at exactly one point $D$ between $A$ and $C$
given
2. $B \in l$ or $B \notin l$ P or not P thm (case 1:)
3. Assume $B \in l$
4. $B \in A B$ def segment
5. $l$ intersects $A B$ def intersect; 3,4
6. $l$ intersects $A B$ or $l$ intersects $B C$
7. $\leftarrow$
(case 2:)
8. Assume $B \notin l$
9. $A \notin l$ def exactly one; 1
10. ( $B$ is on the same side of $l$ as $A$ ) or ( $B$ is on the opposite side of $l$ as $A$ ) separation axiom (S6);8,9
(case a:)
11. $\quad$ Assume $B$ is on the opposite side of $l$ as $A$
12. $l$ intersects $A B$
separation axiom (S6);11
13. $l$ intersects $A B$ or $l$ intersects $B C$ or+
14. $\leftarrow$
15. (case b:)
16. $\quad$ Assume $B$ is on the same side of $l$ as $A$
17. $\quad A C$ intersects $l$ at $D$ copy; 1
18. $A$ is on the opposite side of $l$ as $C$
19. $\quad B$ is on the opposite side of $l$ as $C$
20. $l$ intersects $B C$ separation axiom (S6)
21. $l$ intersects $A B$ or $l$ intersects $B C$
or+
22. $\leftarrow$
23. $l$ intersects $A B$ or $l$ intersects $B C$
or-; $10,11,13,16,21$
24. $\leftarrow$
25. $l$ intersects $A B$ or $l$ intersects $B C$

QED
Lemma (segment subset ray subset line) Let $A, B$ be distinct points. Then $A B \subseteq \overrightarrow{A B} \subseteq \overleftrightarrow{A B}$

## Proof:

1. Let $A, B$ be distinct points
given
2. Let $X \in A B$
3. $X=A$ or $X=B$ or $A \cdot X . B$ def segment
4. $X=A$ or $X=B$ or $A \cdot X \cdot B$ or $A \cdot B \cdot X$ or+
5. $X \in \overrightarrow{A B}$
6. $A B \subseteq \overrightarrow{A B}$
7. Let $Y \in \overrightarrow{A B}$
8. $Y=A$ or $Y=B$ or $A \cdot Y \cdot B$ or $A \cdot B . Y$ def ray (case 1)
9. Assume $Y=A$ or $Y=B$
10. $Y \in \overleftrightarrow{A B}$
11. $\leftarrow$
(case 2)
12. Assume A.Y.B or A.B.Y
13. $Y \in \overleftrightarrow{A B}$ def between
14. $\leftarrow$
15. $Y \in \overleftrightarrow{A B}$
or-; $8,9,10,12,13$
16. $\overrightarrow{A B} \subseteq \overleftrightarrow{A B}$
def subset;7,15
QED
Lemma (intersect all supersets) If $F, G, H$ are figures with $G \subseteq H$. If $F$ intersects $G$ then $F$ intersects $H$.

## Proof:

1. $F, G, H$ are figures given
2. $G \subseteq H$ given
3. $F$ intersects $G$ given
4. There exists $X$ with $X \in F$ and $X \in G$ def intersects
5. $X \in H$
def subset;2,4
6. There exists $X$ with $X \in F$ and $X \in H \quad \exists+; 4,5$
7. $F$ intersects $H$ def intersects

QED
Lemma (opposites don't attract) Let $A, B$ be distinct points and $C, D$ on opposite sides of $\overleftrightarrow{A B}$. Then $\overrightarrow{A C}$ does not intersect $\overrightarrow{B D}$.

## Proof:

1. Let $A, B$ be distinct points and $C, D$ on opposite sides of $\overleftrightarrow{A B}$
given
2. Let $X$ be an arbitrary point on $\overrightarrow{A C}$
3. $X=A$ or $X$ is on the same side of $\overleftrightarrow{A B}$ as $C \quad$ ray-half plane thm
4. Assume $X$ is on $\overrightarrow{B D}$
5. $X=B$ or $X$ is on the same side of $\overleftrightarrow{A B}$ as $D$ ray-half plane thm (case 1)
6. Assume $X=B$
7. $X \neq A$ def distinct; 1
8. $X$ is not on the same side of $\overleftrightarrow{A B}$ as $C$
9. $\sim(X=A$ or $X$ is on the same side of $\overleftrightarrow{A B}$ as $C)$ separation axiom (S6);6
10. $\rightarrow \leftarrow$

DeMorgan's Law;7,8
11. $\leftarrow$
(case 2)
12. Assume $X$ is on the same side of $\overleftrightarrow{A B}$ as $D$
13. $X \neq A$
14. $X$ is on the oppositite side of $\overleftrightarrow{A B}$ as $C$
sides lemma; 1,12
15. $X$ is not on the same side of $\overleftrightarrow{A B}$ as $C$ separation axiom (S6)
16. $\sim(X=A$ or $X$ is on the same side of $\overleftrightarrow{A B}$ as $C)$

DeMorgan's Law;7,8
17. $\rightarrow \leftarrow$
18. $\leftarrow$
19. $\rightarrow \leftarrow$
or-;5,6,10,12,17
20. $\leftarrow$
21. $X$ is not on $\overrightarrow{B D}$
$\sim+; 4,19$
22. No point $X$ on $\overrightarrow{A C}$ is on $\overrightarrow{B D}$
$\forall+; 2,21$
23. $\overrightarrow{A C}$ does not intersect $\overrightarrow{B D}$
def of intersect
QED
Theorem (crossbar) If $D$ is in the interior of $\angle A$ in $\triangle A B C$ then $\overrightarrow{A D}$ intersects $B C$.


## Proof:

1. $D$ is in the interior of $\angle A$ in $\triangle A B C$ given
2. $A, B, C$ are not collinear and distinct $\operatorname{def} \triangle$
3. There exists $E$ on $\overleftrightarrow{A B}$ such that $E . A . B$ and $|A B|=|A E| \quad$ point plotting thm
4. $A \in E B$
5. $A \in \overleftrightarrow{E B}$
6. $A \in \overleftrightarrow{A D}$ segment subset line lemma
( $\star$ show $B E C$ forms a triangle $\star$ )
7. Assume $E \in \overleftrightarrow{B C}$
8. $\overleftrightarrow{B C}=\overleftrightarrow{E B}$

2 pts det a line (S1)
9. $A \in \overleftrightarrow{B C}$
10. $A, B, C$ are collinear
substitution;8,5
def collinear $\rightarrow \leftarrow+; 10,2$
11. $\rightarrow \leftarrow$

$$
\rightarrow \leftarrow+; 10,2
$$

12. $\leftarrow$
13. $E \notin \overleftrightarrow{B C}$

$$
\sim+; 7,11
$$

14. $E, B, C$ are not collinear
def collinear
( $\star$ ok, now we know it's a triangle $\star$ )
15. $\overleftrightarrow{A D}$ intersects side $B E$ of $\triangle B E C$ at $A$
def intersects;4,5
( $\star$ Here's a key idea $\star$ )
16. $\overleftrightarrow{A D}$ intersects $B C$ or $\overleftrightarrow{A D}$ intersects $C E \quad$ Pasch's Theorem
( $\star$ So all we have to show is that it doesn't intersect $C E \star$ )
17. $D$ is on the same side of $\overleftrightarrow{A C}$ as $B$
18. $A \in \overleftrightarrow{A C}$
19. $E B$ intersects $\overleftrightarrow{A C}$
20. $E$ is on the opposite side of $\overleftrightarrow{A C}$ as $B$
21. $D$ is on the opposite side of $\overleftrightarrow{A C}$ as $E$
22. $\overrightarrow{A D}$ does not intersect $\overrightarrow{C E}$
23. $C E \subseteq \overrightarrow{C E}$
24. $\overrightarrow{A D}$ does not intersect $C E$
25. $D$ is on the same side of $\overleftrightarrow{A B}$ as $C$ contrapositive of intersect all supersets lemma def interior; 1
26. There exists a point $P$ such that $P$.A. $D$
27. $A \in P D$
point plotting thm
28. $P$ is on the opposite side of $\overleftrightarrow{A B}$ as $D$
def segment
separation axiom (S6)
29. $P$ is on the opposite side of $\overleftrightarrow{A B}$ as $C$
sides lemma25,28
30. $\overrightarrow{A P}$ does not intersect $\overrightarrow{E C}$
opposites don't attract lemma;2;20;21
31. $E C \subseteq \overrightarrow{E C}$
segment subset ray lemma
32. $\overrightarrow{A P}$ does not intersect $C E$ contrapositive of intersect all supersets lemma; 30,31
33. $\overleftrightarrow{A D}=\overrightarrow{A D} \cup \overrightarrow{A P}$

SMSG Thm 11
34. $\overleftrightarrow{A D} \cap C E=(\overrightarrow{A D} \cup \overrightarrow{A P}) \cap C E$
35. $\quad=(\overrightarrow{A D} \cap C E) \cup(\overrightarrow{A P} \cap C E)$
36. $\quad=\varnothing \cup \varnothing$
37. $\quad=\varnothing$
38. $\overleftrightarrow{A D}$ does not intersect $C E$
39. $\overleftrightarrow{A D}$ intersects $B C$
40. There exists a point $Q$ on $\overleftrightarrow{A D}$ and $B C$
41. $Q \in \overrightarrow{B C}$
42. $Q$ is on the same side of $\overleftrightarrow{A B}$ as $C$
43. $Q \cdot A \cdot D$ or $A \cdot Q \cdot D$ or $A \cdot D \cdot Q$ or $Q=D$ or $Q=A$
44. $Q . A . D$ or $Q \in \overrightarrow{A D}$
substitution
distributivity of $\cap$ over $\cup$
def intersect;32;24
def union
def intersects; 34,37
alt form of or-; 16,38
def of intersects
segment subset ray thm
ray half-plane thm
SMSG Thm 8
def ray
(case 1)
45. Assume $Q \in \overrightarrow{A D}$
46. $\leftarrow$
(case 2)
47. Assume Q.A.D
48. $A \in Q D$ def segment
49. $A \in \overleftrightarrow{A B}$
$\operatorname{def} \overleftrightarrow{A B}$
50. $Q D$ intersects $\overleftrightarrow{A B}$
51. $Q$ is on the opposite side of $\overleftrightarrow{A B}$ as $D$
52. $Q$ is on the opposite side of $\overleftrightarrow{A B}$ as $C$
53. $Q$ is not on the same side of $\overleftrightarrow{A B}$ as $C$
54. $\rightarrow \leftarrow$
55. $Q \in \overrightarrow{A D}$
def intersects;48,49
56. $\leftarrow$
57. $Q \in \overrightarrow{A D}$
or-;44,45,45,47,55
58. $\overrightarrow{A D}$ intersects $B C$ separation axiom (S6)
sides lemma
definition of opposite
$\rightarrow \leftarrow+; 53,42$
$\rightarrow \leftarrow$ implies anything

QED!
def intersects;57,40

Remark At this point we are going to make another of our transitions from formal to informal proofs. From now on we will only number lines when referring to them in a reason is a key idea in the proof and they are not referred to immediately as illustrated in the following example proofs.

## Theorem (SOCAC) Supplements of the same or congruent angles are congruent.

## Proof:

Let $\angle A$ and $\angle B$ be congruent angles
given
Let $\angle C$ be a supplement of $\angle A$
Let $\angle D$ be a supplement of $\angle B$

| $\|\angle C\|+\|\angle A\|=180$ | def supplement |
| :--- | ---: |
| def supplement |  |
| $\|\angle D\|+\|\angle B\|$ | def $\equiv$ angles |
| $\|\angle A\|=\|\angle B\|$ | substitution |
| $\|\angle C\|+\|\angle A\|=\|\angle D\|+\|\angle A\|$ | algebra |
| $\|\angle C\|=\|\angle D\|$ | def $\equiv$ angles |
| $\angle C \equiv \angle D$ |  |

Theorem (ASA) If $\angle A \equiv \angle D, A B \equiv D E, \angle B \equiv \angle E$ then $\triangle A B C \equiv \triangle D E F$.


## Proof:

1. $A, B, C$ are noncollinear and $D E F$ are noncollinear
given
2. $\angle A \equiv \angle D$ given
3. $A B \equiv D E$ given
4. $B \equiv \angle D E F$ given
5. There exists $F^{\prime}$ on $\overrightarrow{D F}$ such that $D F^{\prime} \equiv A C$
$\triangle A B C \equiv \triangle D E F^{\prime}$
6. $\angle B \equiv \angle D E F^{\prime}$

CPOCTAC
$F^{\prime}$ is on the same side of $\overleftrightarrow{D E}$ as $F$
ray half-plane thm
Define $r=\left|\angle D E F^{\prime}\right|$
7. $\overrightarrow{E F^{\prime}}$ is the unique ray in same half-plane of $\overleftrightarrow{D E}$ as $F$ such that $r=\left|\angle D E F^{\prime}\right| \quad$ angle construction axiom (S8)

$$
\begin{array}{rlr}
\left|\angle D E F^{\prime}\right| & =|\angle B| & \text { def } \equiv \text { angles } ; 5 \\
& =|\angle D E F| & \text { def } \equiv \text { angles } ; 3 \\
& =r & \text { copy } \\
\overrightarrow{E F}=\overrightarrow{E F^{\prime}} & \text { def unique } ; 6 \\
F^{\prime} \in \overrightarrow{E F} & \text { def ray } \\
F=F^{\prime} & \text { SMSG Thm 4 } \\
\triangle A B C \equiv \triangle D E F & \text { substitution }
\end{array}
$$

QED

## Theorem (isosceles $\triangle$ ) Two sides in a triangle are congruent if and only if the angles

 opposite those sides are congruent.
## Proof:

Let $A, B, C$ be noncollinear points forming $\triangle A B C$
Define the correspondence $\xi(A)=A, \xi(B)=C, \xi(C)=B$
( $\Rightarrow$ )
Assume $A B \equiv B C$
$\angle A \equiv \angle A$
$\triangle A B C \equiv \triangle A C B$
$\equiv$ is an equiv reln (SMSG Thm 3)
SAS axiom (S11) using $\xi$
CPOCTAC via $\xi$
$(\Leftarrow)$
Assume $\angle B \equiv \angle C$
$B C \equiv B C$
$\equiv$ is an equiv reln (SMSG Thm 3)

$$
\triangle A B C \equiv \triangle A C B
$$

ASA (SMSG Thm 23) using $\xi$
$A B \equiv A C$
QED
Remark In the following proofs we will start to add "connector" words from English to connect the reasons to the statements and to make grammatical transitions from one statement connect to the next. We also add punctutation like periods, etc.

Theorem Angle bisectors exist and are unique.
Comment: You might think that the easy way to prove this is to imitate what we did for the proof that midpoints exist, by using the angle construction axiom to construct a ray of measure half that of the given angle on the appropriate side of one of the rays. But you would be wrong. Try it and see!


## Proof:

Let $\angle B A C^{\prime}$ be an angle.
There exists a point $C$ on $\overrightarrow{A C^{\prime}}$ with $A B \equiv A C \quad$ by the point plotting theorem.
$\triangle A B C$ is isosceles
So $\angle A B C \equiv \angle A C B$
There exists a midpoint $M$ of segment $B C$
Hence $B M \equiv M C$
Thus $\triangle A M B \equiv \triangle A M C$
by the definition of isosceles.

So $\angle B A M \equiv \angle C A M$
by the isosceles triangle theorem.
by SMSG Thm 10.
by the definition of midpoint.
by the SAS axiom (S11).
since CPOCTAC.
Now B.M.C
So $M$ is on $\overrightarrow{B C}$ and $M$ is on $\overrightarrow{C B}$
by the definition of midpoint.
But $M$ is on the same side of $\overleftrightarrow{A C}$ as $B$ and $M$ is on the same side $\leftrightarrows \overleftrightarrow{A B}$ the definition of ray half-plane theorem.
So $M$ is in the interior of $\angle B A C$ by the definition of angle interior.
So $\overrightarrow{A M}$ is the angle bisector of $\angle B A C$ by the definition of angle bisector.
Now suppose $\overrightarrow{A N}$ is also an angle bisector of $\angle B A C$
Then $N$ is in the interior of $\angle B A C$ and $\angle B A N \equiv \angle C A N$ by the definition of angle bisector.

So $\overrightarrow{A N}$ intersects $B C$ at some point $P$
But $A P \equiv A P$
So $\triangle P A B \equiv \triangle P A C$
Therefore $P B \equiv P C$
and thus $P$ is a midpoint of $B C$
by the crossbar theorem.
since $\equiv$ is an equivalence relation.
by the SAS axiom (S11). since CPOCTAC,
by the definition of midpoint.

But midpoints are unique
So $P=M$
Thus, $\overrightarrow{A P}=\overrightarrow{A M}$
and $\overrightarrow{A P}=\overrightarrow{A N}$
So $\overrightarrow{A N}=\overrightarrow{A M}$
So angle bisectors are unique
QED
by SMSG Thm 10. by the definition of unique.
by substitution by the relabeling lemma.
by substitution. by the definition of unique.

Remark Notice that if we eliminate the space between the statements and reasons, and word wrap this we get a typical informal math proof such as those found in most textbooks:

Proof: Let $\angle B A C^{\prime}$ be an angle. There exists a point $C$ on $\overrightarrow{A C^{\prime}}$ with $A B \equiv A C$ by the point plotting theorem. $\triangle A B C$ is isosceles by the definition of isosceles. So $\angle A B C \equiv \angle A C B$ by the isosceles triangle theorem. There exists a midpoint M of segment BC by SMSG Thm 10.
Hence $B M \equiv M C$ by the definition of midpoint. Thus $\triangle A M B \equiv \triangle A M C$ by the SAS axiom (S11). So $\angle B A M \equiv \angle C A M$ since CPOCTAC. Now B.M. C by the definition of midpoint. So $M$ is on $\overrightarrow{B C}$ and $M$ is on $\overrightarrow{C B}$ by the definition of ray. But $M$ is on the same side of $\overleftrightarrow{A C}$ as $B$ and $M$ is on the same side of $\overleftrightarrow{A B}$ as $C$ by the ray half-plane theorem. So $M$ is in the interior of $\angle B A C$ by the definition of angle interior. So $\overrightarrow{A M}$ is the angle bisector of $\angle B A C$ by the definition of angle bisector.

Now suppose $\overrightarrow{A N}$ is also an angle bisector of $\angle B A C$. Then $N$ is in the interior of $\angle B A C$ and $\angle B A N \equiv \angle C A N$ by the definition of angle bisector. So $\overrightarrow{A N}$ intersects $B C$ at some point $P$ by the crossbar theorem. But $A P \equiv A P$ since $\equiv$ is an equivalence relation. So $\triangle P A B \equiv \triangle P A C$ by the SAS axiom (S11). Therefore $P B \equiv P C$ since CPOCTAC and thus $P$ is a midpoint of $B C$ by the definition of midpoint. But midpoints are unique by SMSG Thm 10. So $P=M$ by the definition of unique. Thus, $\overrightarrow{A P}=\overrightarrow{A M}$ by substitution and $\overrightarrow{A P}=\overrightarrow{A N}$ by the relabeling lemma. So $\overrightarrow{A N}=\overrightarrow{A M}$ by substitution. So angle bisectors are unique by the definition of unique. QED

Theorem (SSS) If $A B \equiv D E, B C \equiv E F, A C \equiv D F$ then $\triangle A B C \equiv \triangle D E F$.


## Proof:

Let $\triangle A B C$ and $\triangle D E F$ be triangles with $A C \equiv D F, A B \equiv D E$, and $B C \equiv E F$.
There exists a point $F^{\prime}$ on the opposite side of $\overleftrightarrow{A B}$ as $C$ such that $\angle B A F^{\prime} \equiv \angle D \quad$ by the angle
congstruction axiom (S8).

There exists a point $G$ on $\overrightarrow{A F^{\prime}}$ such that $A G \equiv D F$
Every point of $\overrightarrow{A F^{\prime}}$ other than $A$ is on the same side of $\overleftrightarrow{A B}$
$G$ is on the same side of $\overleftrightarrow{A B}$ as $F^{\prime}$
$G$ is on the opposite side of $\overleftrightarrow{A B}$ as $C$
$C G$ intersects $\overleftrightarrow{A B}$ at some point $H$
$H=A$ or $H=B$ or $H . A . B$ or $A . H . B$ or $A . B . H$
(case 1)
Assume A.H.B
$A G \equiv D F$
$\angle B A F^{\prime} \equiv \angle D$
$A B \equiv A B$
$\triangle A B G \equiv \triangle D E F$
$H$ is in the interior of $\angle A C B$ and $\angle A G B$
$B G \equiv E F$
$B G \equiv B C$
$\angle A C G \equiv \angle A G C$
$\angle B C G \equiv \angle B G C$
$|\angle A C G|=|\angle A G C|$ and $|\angle B C G|=|\angle B G C|$
$|\angle A C B|=|\angle A C G|+|\angle B C G|$
$=|\angle A G C|+|\angle B G C|$
$=|\angle A G B|$
$\angle A C B \equiv \angle A G B$
$A G \equiv A C$
$B C \equiv E F$
So $\triangle A B C \equiv \triangle A B G$
Thus $\triangle A B C \equiv \triangle D E F$
$\leftarrow$
( $\star$ the other cases are similar and are omitted $\star$ )
QED
by the point plotting theorem.
by the ray half-plane thm. by $\forall-$.
by the sides lemma.
by the separation axiom (S6).
by SMSG Thm 8.
from above (aka copy).
also from above.
by reflexivity of $\equiv$.
by SAS (S11).
by SMSG Thm 17. since CPOCTAC. by transitivity of $\equiv$. by the isosceles $\triangle$ thm applied to $\triangle A C G$. by the isosceles $\triangle$ thm applied to $\triangle B C G$. by the definition of congruent segments. by the angle addition axiom (S7). by substitution. by the angle addition axiom (S7). by the definition of congruent segments. by transitivity of $\equiv$. from above.
by SAS (S11). by transitivity of $\equiv$.

Remark In the following proof we continue to make our proofs more informal. In additions to omitting all but essential line numbers, we now eliminate all but essential reasons, and in addition skip non-essential steps. For example, if a statement only has one main logical operation, or only one thing has been modified in going from one statement to the next, then it is usually obvious what the reason is. Also the rules of logic are so well used by this point that it is usually clear when you are doing an or-, implies+, proof by contradiction, etc. at this point and so no reason need to be given.

Another shortcut we introduce here is that instead of referring to a previous line or lines by giving their line numbers in a reason, we might simply restate the needed information as part of the reason for a statement. For example, "so $\angle B A R \equiv \angle B A P$ by the definition of congruent angles since they have the same measure." in the following proof.

Theorem (existance of perpendiculars) Through a given point there exists a line
perpendicular to a given line.


## Proof:

Let $\overleftrightarrow{A B}$ be a line and $P$ a point.
Either $P \in \overleftrightarrow{A B}$ or $P \notin \overleftrightarrow{A B}$
(case 1)
Assume $P \in \overleftrightarrow{A B}$.
There exists a unique ray $\overrightarrow{C P}$ such that $|\angle B P C|=90($ or $|\angle A P C|=90$ if $P=B)$ by the angle construction axiom (S8).
$\overleftrightarrow{C P} \perp \overleftrightarrow{A B}$ by def of perpendicular.
So there is a perpendicular to $\overleftrightarrow{A B}$ through $P$.
$\leftarrow$
(case 2)
Assume $P \notin \overleftrightarrow{A B}$.
There is a ray $\overrightarrow{A R^{\prime}}$ with $R^{\prime}$ on the opposite side of $\overleftrightarrow{A B}$ as $P$ such that $\left|\angle B A R^{\prime}\right|=|\angle B A P|$ by the angle construction axiom (S8).

There exists a point $R$ on $\overrightarrow{A R^{\prime}}$ such that $A R \equiv A P$ by the point plotting theorem.
(*we will show that $\overleftrightarrow{R P} \perp \overleftrightarrow{A B} \star$ )
$R$ is on the same side of $\overleftrightarrow{A B}$ as $R$ by the ray half-plane theorem.
So $R$ is on the opposite side of $\overleftrightarrow{A B}$ as $P$ by the sides lemma.
Thus $R P$ intersects $\overleftrightarrow{A B}$ at some point $F$ with $R . F . P$ by the separation axiom (S6).
$\angle B A R=\angle B A R^{\prime}$ by the relabeling lemma,
so $|\angle B A R|=\left|\angle B A R^{\prime}\right|$ by substitution,
$=|\angle B A P|$ from above.
so $\angle B A R \equiv \angle B A P$ by the definition of congruent angles since they have the same measure.
Either $F=A$ or $F \neq A$.
(case a)
Assume $F=A$
$A$ is on $R P$ and $R . F . P$ by substitution.
$R, A, P$ are collinear by definition of between.
$\angle B A R \equiv \angle B A P$ are a linear pair by definition of linear pair.
$\angle B A R, B A P$ are right angles by definition of right angle since they have equal measure.
So $\overleftrightarrow{R P} \perp \overleftrightarrow{A B}$ by definition of perpendicular.
(case b)
Assume $F \neq A$.
$F . A . B$ or $A . F . B$ or $A . B . F$ or $F=B$ by SMSG Thm 8 .
$F . A . B$ or $F \in \overrightarrow{A B}$ by definition of ray.
(case i)
Assume $F \in \overrightarrow{A B}$
$\angle B A P=\angle F A P$ and $\angle B A R=\angle F A R$ by relabeling.
$\angle F A R \equiv \angle F A P$ by substitution.
$\leftarrow$
(case ii)
Assume F.A.B
$\angle F A P, \angle B A P$ are a linear pair and
$\angle F A R, \angle B A R$ are a linear pair by the definition of linear pair.
$\angle F A P, \angle B A P$ are supplementary and
$\angle F A R, \angle B A R$ are supplementary by the supplement axiom (S10).
$\angle F A R \equiv \angle F A P$ since SOCAC .
$\leftarrow$
$\angle F A R \equiv \angle F A P$ in both cases.
$A F \equiv A F$ since congruence is reflexive.
$A R \equiv A P$ by above.
So $\triangle A F P \equiv \triangle A F R$ by SAS axiom (S11).
$\angle A F P \equiv \angle A F R$ because CPOCTAC.
$\overrightarrow{F R}, \overrightarrow{F P}$ are opposite by definition of opposite.
$\angle A F P, \angle A F R$ are a linear pair by definition of linear pair.
$\overleftrightarrow{R P} \perp \overleftrightarrow{A B}$ by definition of perpendicular.
$\overleftrightarrow{R P} \perp \overleftrightarrow{A B}$ in both cases
So there is a perpendicular to $\overleftrightarrow{A B}$ through $P$.

So there is a perpendicular to $\overleftrightarrow{A B}$ through $P$ in every case QED

Remark Note to prove that the perpendicular through a point to a line is unique we will need the following theorem.

Theorem (exterior angle) The measure of an exterior angle of a triangle is greater than the measure of either of the two opposite angles.

## Proof:

Let $\triangle A B C$ be a triangle and $D$ a point on $\overrightarrow{A C}$ with $A$.C.D.
There exists a unique midpoint $M$ of $B C$ by SMSG Thm 10 . $B M \equiv C M$ by definition of midpoint.
There exists a point $P$ on $\overrightarrow{A M}$ with $M P \equiv M A$ and $A . M . P$ by the point plotting theorem.
$\angle A M B \equiv \angle C M P$ since vertical angles are equal.
Thus, $\triangle A M B \equiv C M P$ by SAS.
(*) $\angle P C B \equiv \angle B$ since CPOCTAC.
( $\star$ we now want to show that $P$ is in the interior of $\angle D C B \star$ )
$M$ is in the interior of $\angle B A C$ by SMSG Thm 17.
$M$ is on the same side of $\overleftrightarrow{A C}$ as $B$ by definition of interior.
$P$ is on the same side of $\overleftrightarrow{A C}$ as $M$ by the ray half-plane theorem.
$P$ is on the same side of $\overleftrightarrow{A C}$ as $B$ by the sides lemma.
$D$ is on the opposite side of $\overleftrightarrow{B C}$ as $A$ by the separation axiom, since $A D$ intersects $\overleftrightarrow{B C}$ at $C$.
$P$ is on the opposite side of $\overleftrightarrow{B C}$ as $A$ by the separation axiom, since $A P$ intersects $\overleftrightarrow{B C}$ at $M$.
$P$ is on the same side of $\overleftrightarrow{B C}$ as $D$ by the sides lemma.
$|\angle P C D|>0$ by the angle measure axiom.
$|\angle B C D|=|\angle P C D|+|\angle P C B|$ by the angle addition axiom $>|\angle P C B|$ by algebra.
$=|\angle B|$ by definition of congruent angles.
Similarly, if $E$ is a point on $\overrightarrow{B C}$ with $B$. C.E then $|E C A|>|C A B|$.
But $|\angle E C A|=|\angle B C D|$ since vertical angles are congruent.
So $|\angle B C D|>|\angle C A B|$ by substitution.
Thus, $|\angle B C D|$ is greater than either of the measures of the two opposite angles in $\triangle A B C$.
QED

## Theorem (uniqueness of perpendiculars) Through a given point there exists a unique line

 perpendicular to a given line.
## Proof:

Let $\overleftrightarrow{A B}$ be a line and $P$ a point.
Either $P \in \overleftrightarrow{A B}$ or $P \notin \overleftrightarrow{A B}$.
(case 1)
Assume $P \in \overleftrightarrow{A B}$
There exists a unique ray $\overrightarrow{C P}$ such that $|\angle B P C|=90($ or $|\angle A P C|=90$ if $P=B$ ) by the angle construction axiom (S8).
$\overleftrightarrow{C P} \perp \overleftrightarrow{A B}$ by def of perpendicular.
So there is a unique perpendicular to $\overleftrightarrow{A B}$ through $P$ since $\overrightarrow{C P}$ is unique.
$\leftarrow$
(case 2)
Assume $P \notin \overleftrightarrow{A B}$
There exists a line $\overleftrightarrow{P F} \perp \overleftrightarrow{A B}$ with $F \in \overleftrightarrow{A B}$ by the existance of perpendiculars theorem.
Let $\overleftrightarrow{A G}$ be a arbitrary line perpendicular to $\overleftrightarrow{A B}$ at $G$.
Assume $G \neq F$.
There exists $H \in \overleftrightarrow{A B}$ with $F . G . H$ by the point plotting theorem.
$\angle H G A$ and $\angle G F A$ are right angles.
All right angles have equal measure by SMSG Thm 21.
So $|\angle H G A|=|\angle G F A|$ by forall minus.
$\angle G F A$ is an exterior angle of $\triangle A F G$ by definition of exterior angle.
$|\angle G F A|>|\angle H G A|$ by the exterior angle theorem.
$|\angle G F A| \neq|\angle H G A|$ by trichotomy.
$\rightarrow \leftarrow$ since we showed these measures are both equal and not equal.
$\leftarrow$
$G=F$ by proof by contradiction.
$\overleftrightarrow{A G}=\overleftrightarrow{A F}$ by substitution.
So there is a unique perpendicular to $\overleftrightarrow{A B}$ through $P$ by definition of unique.
So there is a unique perpendicular to $\overleftrightarrow{A B}$ through $P$ by proof by cases
QED

## Theorem (AAS) If $\angle A \equiv \angle D, \angle B \equiv \angle E$, and $B C \equiv E F$ then $\triangle A B C \equiv \triangle D E F$.

## Proof:

Let $\triangle A B C$ and $\triangle D E F$ be triangles with $\angle A \equiv \angle D, \angle B \equiv \angle E$, and $B C \equiv E F$.
There exists $P$ on $\overrightarrow{A B}$ with $A P \equiv E D$ by the point plotting theorem.
$\triangle P A C \equiv \triangle D E F$ by SAS.
$\angle B P C \equiv \angle D$ by CPOCTAC.
$\angle B P C \equiv \angle A$ since $\equiv$ is transitive.
$|\angle B P C|=|\angle A|$ by definition of $\equiv$ angles.
B.P.A or B.A.P or $P=A$
(case 1)
Assume B. P. A
$\angle B P C$ is an exterior angle of $\triangle P A C$ by definition of exterior angle.
$|\angle B P C|>|\angle A|$ by the exterior angle theorem.
$|\angle B P C| \neq|\angle A|$ by trichotomy.
$\rightarrow \leftarrow$ since the measures are both equal and not equal.
$P=A$ since a contradiction implies anything.
$\leftarrow$
(case 2)
Assume B.A.P
$\angle A$ is an exterior angle of $\triangle P A C$ by definition of exterior angle.
$|\angle A|>|\angle B P C|$ by the exterior angle theorem.
$|\angle B P C| \neq|\angle A|$ by trichotomy.
$\rightarrow \leftarrow$ since the measures are both equal and not equal.
$P=A$ since a contradiction implies anything.
$\leftarrow$
(case 3)
Assume $P=A$
So $P=A$ by proof by cases.
$\triangle A B C \equiv \triangle D E F$ by substitution.
QED

Lemma (order lemma) If $C$ is on $\overrightarrow{A B}$ then $|A C|>|A B|$ if and only if $A . B . C$.
Proof: The proof is left as an easy exercise in using axioms S2, S3, and S4.
Theorem (big angle, big side) In $\triangle A B C,|\angle A|>|\angle B|$ if and only if $a>b$ (i.e.
$|B C|>|A C|$.

## Proof:

Let $\triangle A B C$ be a triangle.
$(\Leftarrow)$
Assume $|B C|>|A C|$
There exists $D$ on $\overrightarrow{C A}$ such that $|D C|=|B C|$ by the point plotting theorem. $|D C|>|A C|$ by substitution.
C.A.D by the order lemma.
$A$ is in the interior of $\angle C B D$ by SMSG Thm 17 .
$|\angle A B D|>0$ by the angle measure axiom (S7).
$|\angle C B D|=|\angle C B A|+|\angle A B D|$ by the angle addition axiom (S9).
$>|\angle C B A|$ by algebra.
$\triangle B C D$ is isosceles by the definition of isoceles.
$\angle C B D \equiv \angle D$ since CPOCTAC.
$|\angle C B D|=|\angle D|$ by the definition of $\equiv$ angles.
$|\angle D|>|\angle C B A|$ by substitution.
$\angle B A C$ is an external angle of $\triangle A B D$ by definition of external angle.
$|\angle B A C|>|\angle D|$ by the external angle theorem.
$>|\angle C B A|$ from above.
So $|\angle B A C|>|\angle C B A|$ by the transitivity of $>$.
( $\star$ Note: This is an interesting example of how you can sometimes use one half of an $\Leftrightarrow$ theorem to prove the other $\star$ )

Assume $|\angle A|>|\angle B|$.
$|B C|>|A C|$ or $|B C|=|A C|$ or $|B C|<|A C|$ by trichotomy.
(case 1)
Assume $|B C|>|A C|$.
$\leftarrow$
(case 2)
Assume $|B C|=|A C|$
$\triangle A B C$ is isosceles by definition of isosceles.
$|\angle A|=|\angle B|$ by the isosceles triangle theorem.
$|\angle A| \neq|\angle B|$ by the trichotomy law since $|\angle A|>|\angle B|$.
$\rightarrow \leftarrow$ since these lengths are equal and not equal.
$|B C|>|A C|$ since a contradiction implies anything.

## $\leftarrow$

(case 3)
Assume $|B C|<|A C|$
$|\angle A|<|\angle B|$ by the $(\Leftarrow)$ direction of this theorem.
$|\angle A| \nsubseteq|\angle B|$ by the trichotomy law since $|\angle A|>|\angle B|$.
$\rightarrow \leftarrow$ since the previous statement is the negation of the one before it.
$|B C|>|A C|$ since a contradiction implies anything.
$\leftarrow$
$|B C|>|A C|$ by proof by cases.
QED

Theorem (triangle inequality) The sum of the lengths of two sides of a triangle is greater than the length of the third side.

## Proof:

Let $\triangle A B C$ be a triangle.
( $\star$ WLOG it suffices to show $|A B|+|B C|>|A C| \star$ )
There exists $D$ on $\overrightarrow{A B}$ with $B D \equiv B C$ and $A . B . D$ by the point plotting theorem.
So $\triangle C B D$ is isosceles.
$\angle D \equiv \angle B C D$ by the isosceles triangle theorem.
$B$ is in the interior of $\angle A C D$ by SMSG Thm 17.
$|\angle A C B|>0$ by the angle measure axiom (S7).
$|\angle A C D|=|\angle A C B|+|\angle B C D|$ by the angle addition axiom (S9).
$>|\angle B C D|$ by algebra.
$=|\angle D|$ by the definition of $\equiv$ angles.
So $|A C|<|A D|$ by the big side, big angle theorem applied to $\triangle D A C$.
$=|A B|+|A C|$ by the definition of between.
QED
Lemma (converse of the vertical angles theorem) If $\overrightarrow{A B}$ and $\overrightarrow{A C}$ are opposite rays and $P, R$ are on opposite sides of $\overleftrightarrow{A B}$ such that $\angle C A R \equiv \angle B A P$ then $P, A, R$ are collinear and hence $\angle C A R$ and $\angle B A P$ are vertical angles.

## Proof:

Let $\overrightarrow{A B}$ and $\overrightarrow{A C}$ be opposite rays and $P, R$ on opposite sides of $\overleftrightarrow{A B}$ such that $\angle C A R \equiv \angle B A P$. $|\angle C A R|=|\angle B A P|$ by definition of $\equiv$ angles.
$\angle C A R, \angle B A R$ form a linear pair by definition of linear pair.
$\angle C A R, \angle B A R$ are supplementary by the supplement axiom (S10).
$|\angle C A R|+|\angle B A R|=180$ by the definition of supplement.
$|\angle B A P|+|\angle B A R|=180$ by substitution.
$|\angle B A P|=180-|\angle B A R|$ by algebra.
Define $P^{\prime}$ such that $\overrightarrow{A P}$ and $\overrightarrow{A P^{\prime}}$ are opposite rays.
$\angle B A P^{\prime}$ and $\angle B A P$ are a linear pair.
$\angle B A P^{\prime}, \angle B A P$ are supplementary by the supplement axiom (S10).
$|\angle B A P|+\left|\angle B A P^{\prime}\right|=180$ by the definition of supplement.
$|\angle B A P|=180-\left|\angle B A P^{\prime}\right|$ by algebra.
So $180-|\angle B A R|=180-\left|\angle B A P^{\prime}\right|$ by substitution and
$|\angle B A R|=\left|\angle B A P^{\prime}\right|$ by algebra.
Define $r=|\angle B A R|$.
There is a unique ray with vertex $A$ on the half-plane of $\overleftrightarrow{A B}$ making an angle of measure $r$ with $\overrightarrow{A B}$ by the angle construction axiom.
$\overrightarrow{A R}=\overrightarrow{A P^{\prime}}$ by definition of unique.
$\overrightarrow{A R}$ is the opposite ray to $\overrightarrow{A P}$ by substitution.
$P, A, R$ are collinear by the definition of opposite.
$\angle P A B$ and $\angle C A R$ are vertical angles by the definition of vertical angle.
QED

Theorem (alternate interior angle) If two lines are cut by a transversal then the two lines are parallel if and only if the alternate interior angles formed are congruent.

## Proof:

Let $l, m, n$ be lines with $m \| n$ and $l$ a transversal meeting $m, n$ at $A$ and $B$ respectively.
$(\Leftarrow)$
Assume $C \in m$ and $D \in n$ are points on opposite sides of $l$ with $\angle C A B \equiv \angle A B D$. $|\angle A B D|=|\angle C A B|$ by definition of $\equiv$.
There exists a midpoint $M$ of $A B$ by the midpoint theorem.
$A M \equiv B M$ by definition of midpoint.
$|\angle C A B|=90$ or $|\angle C A B| \neq 90$.
(case 1)
Assume $|\angle C A B|=90$.
$|\angle A B D|=90$ by substitution.
$l \perp m$ and $l \perp n$ by definition of perpendicular.
$m \| n$ by the common perpendicular theorem.
$\leftarrow$
(case 2)
Assume $|\angle C A B| \neq 90$.
$|\angle A B D| \neq 90$ by substitution.
There exists a unique perpendicular $\overleftrightarrow{M C}$ through $M$ to $m$ meeting $m$ at $E$ by the uniqueness of perpendiculars theorem.

There exists a unique perpendicular $\overleftrightarrow{M D}$ through $M$ to $n$ meeting $n$ at $F$ by the uniqueness of perpendiculars theorem.
$\triangle M E A \equiv \triangle M F B$ by AAS.
$\angle A M E \equiv \angle B M F$ since CPOCTAC.
$E, M, F$ are collinear by the converse of the vertical angles theorem.
$\overleftrightarrow{E F}$ is a common perpendicular to $m$ and $n$.
$m \| n$ by the common perpendicular theorem.
$\leftarrow$
$m \| n$ in both cases.

Assume $m \| n$.
There exists a point $D^{\prime}$ on $n$ such that $B \neq D^{\prime}$ since every line has infinitely many points.
There exists $C^{\prime}$ on the opposite side of $\overleftrightarrow{A B}$ from $D$ such that $\left|\angle B A C^{\prime}\right|=\left|D^{\prime} B A\right|$ by the angle construction axiom (S8).
$\overleftrightarrow{A C^{\prime}} \| n$ by the $(\Leftarrow)$ direction of this theorem proven above.
$\overleftrightarrow{A C^{\prime}}$ and $m$ are both parallel to $n$ and contain $A$
$(\star$ Note that the following line is the first place we are using the parallel axiom, so this is the first SMSG theorem in our list that does not apply to both Euclidean and hyperbolic geometry, but rather just to Euclidean. $\star$ )

There exists a unique line through $A$ parallel to $n$ by the parallel axiom (S12).
$m=\overleftrightarrow{A C^{\prime}}$ by the definition of unique.
$m$ makes congruent alternate interior angles with $\overleftrightarrow{A B}$ by substitution
QED

Theorem ( $\triangle$ sum) The sum of the measures of the angles in a triangle is 180.

## Proof:

Let $\triangle A B C$ be a triangle.
There exists a unique line $l$ through $A$ which is parallel to $\overleftrightarrow{B C}$ by the parallel axiom (S12).
There exist $P, Q$ on $l$ with $P . A . Q$ by the point plotting theorem.
$\angle Q A C, \angle P A C$ are a linear pair.
$|\angle Q A C|+|\angle P A C|=180$ by the supplement axiom (S10)..
( $\star$ WLOG we can assume $P$ is on same side of $\overleftrightarrow{A C}$ from $B \star$ )
$\angle P A B \equiv \angle B$ and $\angle Q A C \equiv \angle C$ by the alternate interior angle theorem.
$|\angle P A B|=|\angle B|$ and $|\angle Q A C|=|\angle C|$ by the definition of $\equiv$ angles.
$B$ is on the same side of $l$ as $C$ by the separation axiom since $B C$ doesn't intersect $l$.
$B$ is on the same side of $\overleftrightarrow{A C}$ as $P$ from above.
So $B$ is in the interior of $\angle P A C$.
$|\angle P A C|=|\angle P A B|+|\angle B A C|$ by the angle addition axiom (S9).
$|\angle P A B|+|\angle B A C|+|\angle Q A C|=180$ by substitution.
$|\angle B|+|\angle B A C|+|\angle C|=180$ by substitution.
QED

## Lemma (intersect one-intersect all) If one line intersects a second dstinct line it must intersect every line in the parallel class of the second line as well.

## Proof:

$\mathbb{E}$ is an affine plance by SMSG Thm 2.
In any affine plane, if one line intersects a second distinct line it must intersect every line in the parallel class of the second line as well by the theorem proved for homework in Affine Plane Part II \#1.

QED

Theorem (parallel projection) Let $A, B, C, D$ be distinct points on line $l$ with $A B \equiv C D$ and $A^{\prime}, B^{\prime}, C^{\prime}, D^{\prime}$ points on $m$ such that $A A^{\prime}\left\|B B^{\prime}\right\| C C^{\prime} \| D D^{\prime}$ then $A^{\prime} B^{\prime} \equiv C^{\prime} D^{\prime}$.

## Proof:

Let $A, B, C, D$ be distinct points on line $l$ with $A B \equiv C D$.
Let $A^{\prime}, B^{\prime}, C^{\prime}, D^{\prime}$ points on $m$ such that $A A^{\prime}\left\|B B^{\prime}\right\| C C^{\prime} \| D D^{\prime}$.
There exists a unique line $q$ through $A$ parallel to $m$ by the parallel axiom (S12).
There exists a unique line $r$ through $C$ parallel to $m$ by the parallel axiom (S12).
The Euclidean place is an affine plane by SMSG Thm 2.
$q$ intersects $B B^{\prime}$ at some unique point $Q$ and $r$ intersects $D D^{\prime}$ at some unique point $R$ by the intersect one-intersect all lemma.
$A Q B^{\prime} A^{\prime}, C R D^{\prime} C^{\prime}$ are parallelograms.
$A Q \equiv A^{\prime} B^{\prime}$ and $C R \equiv C^{\prime} D^{\prime}$ by the parallelogram theorem (SMSG Thm 47).
$l \| m$ or $l \| m$.
(case 1)
Assume $l \| m$
$l=q=r$ and $Q=B$ and $R=D$ by definition of unique.
$A B \equiv A^{\prime} B^{\prime}$ and $C D \equiv C^{\prime} D^{\prime}$ by substitution.
$A^{\prime} B^{\prime} \equiv C^{\prime} D^{\prime}$ by transitivity of $\equiv$.
$\leftarrow$
(case 2)
Assume $l|\mid 1$ m.
Assume $q=r$.
$A$ is on $r$ by substitution.
$r=\overleftrightarrow{A C}(=l)$ because two points determine a line (S1)
$l \| m$ by substitution.
$\rightarrow \leftarrow$
$\leftarrow$
$q \neq r$ by proof by contradiction.
$q \| r$ by SMSG Thm 42.
$\angle Q A B \equiv \angle R C D$ by the corresponding angles theorem.
$\angle A B Q \equiv \angle C D R$ by the corresponding angles theorem.
$\triangle A B Q \equiv \triangle C D R$ by ASA.
$A Q \equiv C R$ since CPOCTAC.
$A^{\prime} B^{\prime} \equiv C^{\prime} D^{\prime}$ by transitivity of $\equiv$.
$A^{\prime} B^{\prime} \equiv C^{\prime} D^{\prime}$ in both cases.
QED
Theorem (area of a triangle) The area of a triangle is half of the product of an altitude and its corresponding base.

## Proof:

( $\star$ We first prove this for right triangles $\star$ )
Let $\triangle P Q R$ be a right triangle with right angle at $P$.
There exists a unique perpendicular $l$ to $\overleftrightarrow{P R}$ through $R$ by the perpendiculars theorem.
$l \| \overleftrightarrow{P Q}$ by the common perpendicular theorem.
There exists a unique line $m$ parallel to $\overleftrightarrow{P R}$ through $Q$ by the parallel axiom. $m$ intersects $l$ at some point $S$ by the intersect one-intersect all lemma.
$P Q R S$ is a parallelogram by definition of parallelogram.
$P Q R S$ is a rectangle by the rectangle theorem.
$\triangle P Q R \equiv \triangle S R Q$ by the parallelogram theorem.
$|\triangle P Q R|=|\triangle S R Q|$ by the congruence preserves areas axiom (S14).
$|P R||P Q|=|P Q R S|$ by the area of a rectangle axiom (S16).
$=|\triangle P Q R|+|\triangle S R Q|$ by the area addition axiom (S15).
$=|\triangle P Q R|+|\triangle P Q R|$ by substitution.
$=2|\triangle P Q R|$ by substitution.
$|\triangle P Q R|=\frac{1}{2}|P R||P Q|$ by algebra.
Thus, every right triangle has area equal to half the product of an altitude and its corresponding base.
( $\star$ Now we can use this for general triangles $\star$ )
Let $\triangle A B C$ be a triangle.
There exists a line through $A$ perpendicular to $\overleftrightarrow{B C}$ meeting $B C$ at some point $H$ by the perpendicular theorem.
$H=B$ or $H=C$ or B.H.C or $H . B . C$ or B.C.H by SMSG Thm 8 .
(case 1)
Assume $H=B$ or $H=C$.
$\triangle A B C$ is a right triangle.
$|\triangle A B C|=\frac{1}{2}|A H||B C|$ by the result proven above.
$\leftarrow$
(case 2)
Assume B.H.C
$\triangle A B C$ is a right triangle.
$|\triangle A B C|=|\triangle A H B|+|\triangle A H C|$ by the area addition axiom (S15).
$=\frac{1}{2}|A H||H B|+\frac{1}{2}|A H||H C|$ by the result proven above.
$=\frac{1}{2}|A H|(|B H|+|H C|)$ by algebra.
$=\frac{1}{2}|A H||B C|$ by the definition of between.
$\leftarrow$
(case 3)
Assume H.B.C.
$\triangle A H B$ and $\triangle A H C$ are right triangles.
$|\triangle A H C|=|\triangle A H B|+|\triangle A B C|$ by the area addition axiom (S15).
$\frac{1}{2}|A H||H C|=\frac{1}{2}|A H||B C|+|\triangle A B C|$ by the result proven above.
$\frac{1}{2}|A H|(|H B|+|H C|)=\frac{1}{2}|A H||B C|+|\triangle A B C|$ by the definition of between.
$|\triangle A B C|=\frac{1}{2}|A H||B C|$ by algebra.
$\leftarrow$
(case 4 is similar to case 3 and is omitted)
$|\triangle A B C|=\frac{1}{2}|A H||B C|$ in every case.
QED

Theorem (Pythagorean Theorem) In any right triangle the square of the length of the hypotenuse is equal to the sum of the squares of the lengths of the legs.

Proof: (See page 9 of Baragar's book for a nice proof. Notice that we can fill in the missing details he mentions after the proof using the SMSG theorems we have proven. For example, squares exist because we can construct them in a manner similar to the rectangle construction in the previous proof above. The area of a square is it's side length squared by the area of a rectangle axiom (S16).)

Theorem (basic proportionality) A segment connecting points on two sides of a triangle is parallel to the third side if and only if the segments it cuts off are proportional to the sides.


## Proof:

Let $\triangle A B C$ be a triangle, $D$ on $A B$, and $E$ on $A C$.
$(\Rightarrow)$
Assume $\overleftrightarrow{D E} \| \overleftrightarrow{B C}$.
There exist altitudes $D H$ and $E H^{\prime}$ of triangles $\triangle D B C$ and $E C B$ respectively by the perpendiculars theorem.
$D H$ and $E H^{\prime}$ are perpendicular to $D E$ by the common perpendicular theorem.
$D E H^{\prime} H$ is a rectangle.
$|D H|=\left|E H^{\prime}\right|$ by the parallelogram theorem.
$|\triangle D B C|=\frac{1}{2}|B C||D H|$ by the area of a triangle theorem.
$=\frac{1}{2}|B C|\left|D H^{\prime}\right|$ by substitution.
$=|\triangle E B C|$ by the area of a triangle theorem.
$|\triangle D A C|+|\triangle D B C|=|\triangle A B C|$ by the area addition axiom (S15).
$=|\triangle E B A|+|\triangle E B C|$ by the area addition axiom (S15).
$=|\triangle E B A|+|\triangle D B C|$ by substitution.
$|\triangle D A C|=|\triangle E B A|$ by algebra.
Define $h$ to be the length of the altitude of $\triangle A B C$ through $C$.
Define $j$ to be the length of the altitude of $\triangle A B C$ through $B$.
$\frac{1}{2} h|A D|=\frac{1}{2} j|A E|$ by the area of a triangle theorem.
$\frac{h}{j}=\frac{|A E|}{|A D|}$ by algebra.
$\frac{1}{2} h|A B|=|\triangle A B C|$ by the area of a triangle theorem.
$=\frac{1}{2} j|A C|$ by the area of a triangle theorem.
$\frac{h}{j}=\frac{|A C|}{|A B|}$ by algebra.
$\frac{|A E|}{|A D|}=\frac{|A C|}{|A B|}$ by substitution.
QED
Theorem (similarity SSS) If $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}=\frac{|B C|}{|E F|}$ then $\triangle A B C \sim \triangle D E F$.
Proof:
Let $\triangle A B C, \triangle D E F$ be triangles with $\frac{|A B|}{|D E|}=\frac{|A C|}{|D F|}=\frac{|B C|}{|E F|} \leq 1$ (WLOG).
There exist $X, Y$ on $D E$ and $D F$ respectively with $|D X|=|A B|$ and $|D Y|=|A C|$ by the point plotting theorem.
$\frac{|D X|}{|D E|}=\frac{|D Y|}{|D F|}$ by substitution.
$\triangle D X Y \sim \triangle A B C$ by the basic proportionality theorem.
$\frac{|X Y|}{|E F|}=\frac{|D Y|}{|D F|}$ by CPOST.
$=\frac{|A C|}{|D F|}$ by substitution.
$=\frac{|B C|}{|E F|}$ by substitution.
$|X Y|=|B C|$ by algebra.
$X Y \equiv B C, D X \equiv A B, D Y \equiv A C$ by definition of $\equiv$ segments.
$\triangle D X Y \equiv \triangle A B C$ by SSS.
$\angle D \equiv \angle A$ since CPOCTAC.
$\triangle A B C \sim \triangle D E F$ by similarity SAS.
QED

Theorem (fundamental theorem for circles) Let l be a line, $\odot O A$ a circle, and $F$ the foot of the perpendicular to $l$ through $O$. Then either
(a) Every point of l is outside the circle, or
(b) $F$ is on the circle and every other point of l is outside the circle (and thus l is a tangent line), or
(c) $F$ is inside the circle and l intersects the circle in two points which are equidistant from $F$.

## Proof:

Let $l$ be a line, $\odot O A$ a circle, and $F$ the foot of the perpendicular to $l$ through $O$.
Define $r=|O A|$.
$|O F|>r$ or $|O F|=r$ or $|O F|<r$
(case 1)
Assume $|O F|>r$.
Let $X \in l$.
$|O X| \geq|O F|$ by the point-to-line distance theorem.
$>r$ from above.
$X$ is outside $\odot O A$ by definition of circle exterior.
Every point of $l$ is outside the circle since $X$ was arbitrary.
$\leftarrow$
(case 2)
Assume $|O F|=r$.
$F \in \odot O A$ by definition of circle.
Let $X \in l$ and $X \neq F$.
$\triangle O F X$ is a right triangle by definition of perpendicular.
$|O X|^{2}=|F X|^{2}+r^{2}$ by the Pythagorean theorem.
$>r^{2}$ by algebra.
$|O X|>r$ by algebra.
$X$ is outside $\odot O A$ by definition of circle exterior.
Every point of $l$ other than $F$ is outside the circle since $X$ was arbitrary.
$F$ is on the circle and every other point of $l$ is outside the circle from above.
$\leftarrow$
(case 3)
Assume $|O F|<r$.
$F$ is inside the circle by definition of circle interior.
There exist points $P, Q$ on both sides of $F$ on $l$ such that $|F P|=|F Q|=\sqrt{r^{2}-|O F|^{2}}$ by the point plotting theorem.
$\triangle P F O, \triangle Q F O$ are right triangles by definition of perpendicular.
$|O P|=|O Q|=r$ by the Pythagorean theorem and algebra.
$P, Q$ are on $\odot O A$ by the definition of circle.
$F$ is inside the circle and $l$ intersects the circle in two points which are equidistant from $F$ from above.

QED

Theorem (Two Circle Theorem) If two circles having radii $a$ and $b$ have centers that are $a$ distance $c$ apart, and if each of $a, b, c$ is less than the sum of the other two, then the two circles intersect at exactly two points, one on each side of the line through their centers.

## Proof:

Let $\odot A A^{\prime}$ and $\odot B B^{\prime}$ be circles with radii $a$ and $b$ respectively and $|A B|=c$ where
any of $a, b, c$ is less than the sum of the other two and wlog assume $a \geq b$.
$a^{2}<b^{2}+c^{2}$ or $a^{2}=b^{2}+c^{2}$ or $a^{2}>b^{2}+c^{2}$ by trichotomy.
(case 1)
Assume $a^{2}<b^{2}+c^{2}$
Define $x=\frac{b^{2}+c^{2}-a^{2}}{2 c}$.
$b-x=b-\frac{b^{2}+c^{2}-a^{2}}{22 c}$ by substitution.
$=\frac{2 b c-b^{2}-c^{2}+a^{2}}{2 c}$ by algebra.
$=\frac{a^{2}-(b-c)^{2}}{2 c}$ by algebra.
$=\frac{(a+c-b)(a+b-c)}{2 c}$ by algebra.
$>0$ by algebra since $a+c>b$ and $a+c>b$ from above.
So $x<b$ by algebra.
$c-x=c-\frac{b^{2}+c^{2}-a^{2}}{2 c}$ by substitution.
$=\frac{2 c^{2}-b^{2}-c^{2}+a^{2}}{2 c}$ by algebra.
$=\frac{a^{2}+c^{2}-b^{2}}{2 c}$ by algebra.
$>\frac{a^{2}+\left(a^{2}-b^{2}\right)-b^{2}}{2 c}$ since $c^{2}>a^{2}-b^{2}$ by the assumption above.
$=\frac{a^{2}-b^{2}}{c}$ by algebra.
$=\frac{(a-b)(a+b)}{c}$ by algebra.
$>0$ since $a \geq b$ from above.
So $x<c$ by algebra.
$a-(c-x)=a-c+\frac{b^{2}+c^{2}-a^{2}}{2 c}$ by substitution.
$=\frac{2 a c-2 c^{2}+b^{2}+c^{2}-a^{2}}{2 c}$ by algebra.
$=\frac{b^{2}-c^{2}+2 a c-a^{2}}{2 c}$ by algebra.
$=\frac{b^{2}-(c-a)^{2}}{2 c}$ by algebra.
$=\frac{(b-c+a)(b+c-a)}{2 c}$ by algebra.
$>0$ by algebra since $a+b>c$ and $b+c>a$ from above.
So $c-x<a$.
There exists a point $P$ on $A B$ with $|B P|=x$ by the point plotting theorem.
$P$ is inside $\odot B B^{\prime}$ by definition of interior since $|B P|<b$.
There exists $\Psi$ on $\overleftrightarrow{A B}$ with $\Psi(B)=0$ and $\Psi(A)>0$ by the ruler placement axiom (S4).
$\Psi(P)=x$ and $\Psi(A)=c$ by the coordinate axiom (S3).
$|A P|=|\Psi(A)-\Psi(P)|$ by the coodinate aciom (S3).
$=|c-x|$ by substitution.
$=c-x$ by algebra since $x<c$.
$<a$ from above.
So $P$ is inside $\odot A A^{\prime}$ by definition of interior since $|A P|<a$.
There exists a unique line $l$ through $P$ that is perpendicular to $\overleftrightarrow{A B}$ by the perpendiculars theorem.
$l$ intersects $\odot B B^{\prime}$ at exactly two points $C, C^{\prime}$ on opposite sides of $\overleftrightarrow{A B}$ by the fundamental theorem for circles.
$l$ intersects $\odot A A^{\prime}$ at exactly two points $S, S^{\prime}$ on opposite sides of $\overleftrightarrow{A B}$ by the fundamental theorem for circles (wlog we can assume $S$ is on the same side as $C$ ).
$\left(a^{2}-(c-x)^{2}\right)=a^{2}-c^{2}+2 x c-x^{2}$ by algebra.
$=a^{2}-c^{2}+2\left(\frac{b^{2}+c^{2}-a^{2}}{2 c}\right) c-x^{2}$ by substitution.
$=a^{2}-c^{2}+b^{2}+c^{2}-a^{2}-x^{2}$ by algebra. $=b^{2}-x^{2}$ by algebra.
$|P S|=\sqrt{a^{2}-(c-x)^{2}}$ by the Pythagorean theorem applied to $\triangle A P S$.
$=\sqrt{b^{2}-x^{2}}$ by substitution.
$=|P C|$ by the Pythagorean theorem applied to $\triangle B P S$.
There exists a unique point on $\overrightarrow{P S}$ whose distance from $P$ is $|P S|$ by the point plotting theorem.
$S=C$ by the definition unique.
$S^{\prime}=C^{\prime}$ by a similar argument.
$\odot A A^{\prime}, \odot B B^{\prime}$ intersect at two points, $C, C^{\prime}$ on each side of $\overleftrightarrow{A B}$ by the definition of intersect.
Let $X$ be any point of intersection of these circles (wlog on the same side of $\overleftrightarrow{A B}$ as $C$ ).
$|A X|=a$ and $|B X|=b$ by definition of circle.
$\triangle A B X \equiv \triangle A B C$ by SSS.
$\angle B A X \equiv \angle B A C$ since CPOCTAC.
$\overrightarrow{A X}=\overrightarrow{A C}$ by the angle construction axiom (S8).
$X, C$ are the unique point on $\overrightarrow{A C}$ at distance $a$ from $A$ by the point plotting theorem.
$X=C$ by the definition of unique.
$\odot A A^{\prime}, \odot B B^{\prime}$ intersect at exactly two points, $C, C^{\prime}$ on each side of $\overleftrightarrow{A B}$
$\leftarrow$
(case 2 and case 3 are similar proofs using $x=0$ and $x=-\frac{b^{2}+c^{2}-a^{2}}{2 c}$ respectively and are omitted)
QED
Theorem (triangle existance) For any positive real numbers $a, b, c$ such that the sum of any two is greater than the third there is a triangle $\triangle A B C$ having side lengths $a, b, c$.

## Proof:

Let $a, b, c$ be positive real numbers such that the sum of any two is greater than the third.
There exists distinct points $A, B^{\prime}$ by the point existance axiom (S5).
There exists $B$ on $\overleftrightarrow{A B^{\prime}}$ such that $|A B|=c$ by the point plotting theorem.
Define $\odot B$ to be the circle of radius $a$ centered at $B$.
Define $\odot A$ to be the circle of radius $b$ centered at $A$.
$\odot A$ intersects $\odot B$ at a point $C$ not on $\overleftrightarrow{A B}$ by the Two Circle Theorem.
$|B C|=a$ and $|A C|=b$ by definition of circle.
$\triangle A B C$ has side lengths $a, b, c$ from above.
QED

## Further Study of Euclidean Geometry

## Lemma (fun with fractions) Let $a, b, x, y, r$ be real numbers. Then

$$
\frac{x}{y}=\frac{a}{b}=r \Rightarrow \frac{x-a}{y-b}=\frac{x+a}{y+b}=r
$$

## Pf:

Let $a, b, x, y, r$ be real numbers.

$$
\begin{aligned}
& \text { Assume } \frac{x}{y}=\frac{a}{b}=r . \\
& a y=b x \\
& x y \pm a y=x y \pm b x \\
& (x \pm a) y=(y \pm b) x \\
& \frac{(x \pm a)}{(y \pm b)}=\frac{x}{y} \\
& \quad=r
\end{aligned}
$$

$$
a y=b x \quad \text { by algebra }
$$

$$
x y \pm a y=x y \pm b x \quad \text { substitution }
$$

QED

Theorem (Angle Bisector Theorem) If $D$ is the point where the angle bisector of $\angle A$ in $\triangle A B C$ meets $B C$ then

$$
\frac{|B D|}{|B A|}=\frac{|C D|}{|C A|}
$$

Proof:


Let $D$ be the point where the angle bisector of $\angle A$ in $\triangle A B C$ meets $B C$ (which exists by the crossbar theorem).
There is a unique line through $B$ parallel to $A D$ by the parallel axiom.
This line intersects $\overleftrightarrow{A C}$ at some point $E$ by the intersect one, intersect all lemma in the proof section below.

$\angle E B A \equiv \angle B A D$ by the alternate interior angles theorem.
$\angle A E B \equiv \angle D A C$ by the corresponding angles theorem.
$\angle B A D \equiv \angle D A C$ by the definition of angle bisector.
So $\angle E B A \equiv \angle A E B$ by transitivity of $\equiv$.
Thus $E A \equiv B A$ by the isosceles triangle theorem,
and $|E A|=|B A|$ by the definition of congruent segments.
$\frac{|C D|}{|C B|}=\frac{|C A|}{|C E|}$ by the basic proportionality theorem.
$\frac{|C D|}{|C A|}=\frac{C B \mid}{|C E|}$ by algebra.
$\frac{|C D|}{|C A|}=\frac{|C B-|C D|}{|C E|-|C A|}$ by the fun with fractions lemma.
$=\frac{|B D|}{|E A|}$ by the definition of between (segment addition).
$=\frac{|B D|}{|B A|}$ by substitution.
QED


[^0]:    Definition Let lbe a Euclidean line in $\mathbb{C}$. Then the direction number of the line $l$ is defined

